



Hand in hand for tomorrow



Product data sheet

Automatic tool changers CPS

Modular. Robust. Flexible. Automatic tool changers CPS

Pneumatically actuated tool changer with self-retaining function in the event of a loss of compressed air, the integrated piston spring ensures that gap formation is minimized.

Field of application

Universally applicable (e.g., for handling tasks or machine loading) with short change-over times between an end effector such as a gripper or a customer's tool.

Advantages – Your benefits

Wide range of sizes with 18 sizes, the CPS enables an optimal selection for every application

Versatile media transmission extensive range of optional modules for feed-through of electrical and fluidic media extends the application possibilities of the tool change system

Durability The use of hardened and stainless steel in all functional parts increases the bearing load capacity and extends the service life

Easy assembly Installation is quick and easy using standardized adapter plates or directly on the mechanical interface



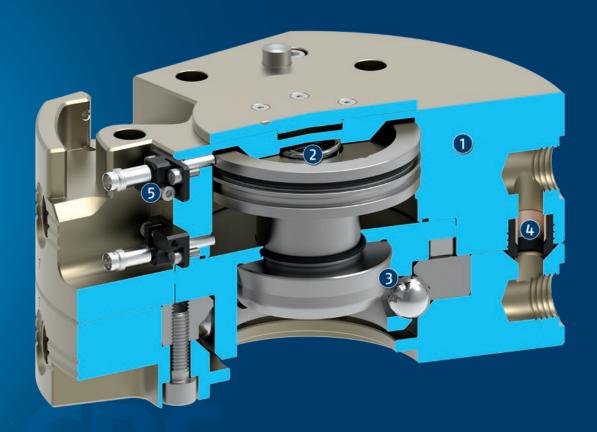




Functional description

The automatic tool changer CPS consists of a change master (CPS-K) and a change adapter (CPS-A). The CPS-K that is mounted on the robot couples and decouples the CPS-A which is mounted on the tool. The pneumatically

actuated locking piston ensures a reliable connection. Suitable option modules supply the coupled tool.



① Housing

Weight-optimized due to the use of high-strength, hard-coated aluminum alloy

② Piston

Pneumatically driven, ensures locking/unlocking of the system

3 Locking mechanism

Functional parts are made of hardened stainless steel. Locking balls ensure a quick and secure connection. Self-retaining during compressed air drop. Integrated spring prevents gap formation between master and adapter.

4 Integrated pneumatic feed-throughs

Minimization of the interfering contour. Also suitable for transferring vacuum.

Sensor monitoring of the locking device Optional, for monitoring in a reliable process

General notes about the series

Actuation: pneumatic, with filtered compressed air as per ISO 8573-1:2010 [7:4:4].

Operating principle: piston-actuated balls with integrated spring (to support the locked piston position)

Media transmission: variable via attachment feed-through modules, depending on the unit size

Housing: The housing consists of high-strength, hard-coated aluminum alloy The functional components are made of hardened corrosion free steel.

Warranty: 24 months

Service life characteristics: on request

Harsh environmental conditions: Please note that use under harsh environmental conditions (e.g. in the coolant area, cast and grinding dust) can considerably reduce the service life of the units, and we will not take over any warranty. However, in many cases we can find a solution. Please contact us for assistance.

Minimum pressure: The minimum pressure is the required minimum pressure to lock the system. This pressure must be continuously present during operation.

Self-retaining: The automatic tool changer has a self-retaining feature that prevents the tool from falling off in case of the pressure drop. The change master and change adapter can be separated by pneumatically actuating the piston.



Application example

- Automatic tool changers CPS
- Optional modules COS
- Modular storage rack CTS
- Universal gripper EGU
- 3 2-finger parallel gripper JGP-P

SCHUNK offers more ...

The following components make the product even more productive - the suitable addition for the highest functionality, flexibility, reliability, and controlled production.







Optional modules COS







Adapter plates

Universal gripper

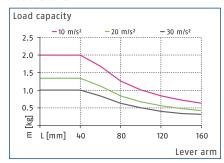


Proximity switch

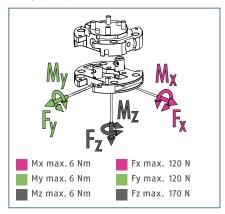
① For more information on these products can be found on the following product pages or at schunk.com.

Modular storage rack CTS





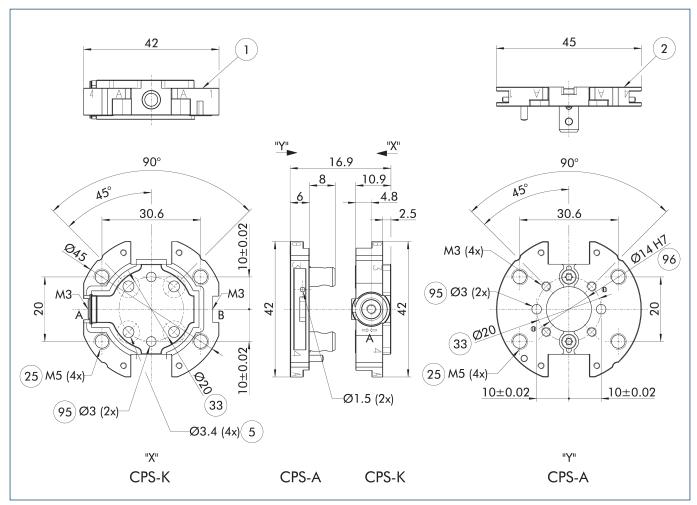
Max. loads



① This is the sum of all static loads that are permitted to act on the tool changer.

Description		CPS 001-K	CPS 001-A
		Change head	Tool
ID		1590948	1619548
Lock sensing		not possible	
Locking force	[N]	170	
Locking force provided by spring force	[N]	4	
Repeat accuracy	[mm]	0.01	
Weight	[kg]	0.03	0.02
Max. distance when locking	[mm]	1	
Number of pneumatic feed-throughs		4x M5	4x M5
Lock/unlock main connection		M3	
Max. permissible XY axis offset	[mm]	±2	±2
Max. permissible angular offset XY	[°]	±0.7	±0.7
Max. permissible angular offset Z	[°]	±1	±1
Min./max. ambient temperature	[°C]	5/60	5/60
Min./max. operating pressure	[bar]	4.5/7	4.517
Screw connection diagram		S1	S1
Opening/closing time	[s]	0.1/0.1	
Cylinder volume per double stroke	[cm³]	1.2	
Max. volumetric flow per pneumatic feed-through		150 I/min (M5)	150 I/min (M5)
Max. dynamic moment Mx	[Nm]	2	2
Max. dynamic moment My	[Nm]	2	2
Max. dynamic moment Mz	[Nm]	2	2
Force Fx max. dynamic	[N]	40	40
Force Fy max. dynamic	[N]	40	40
Force Fz max. dynamic	[N]	57	57

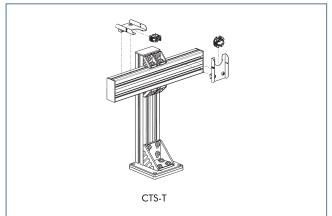
Main view



The drawing shows the basic version of the tool changer without taking account of the dimensions of the options described below.

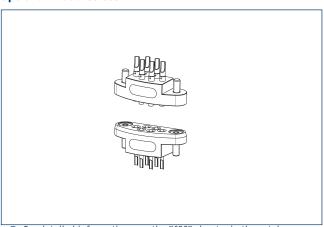
- A, a Air connection locked
- B, b Air connection unlocked
- (1) Robot-side connection
- 2 Tool-side connection
- (5) Through hole for connection with screws
- 24) Bolt circle
- 25) Pneumatic feed-throughs
- 90 Groove for tool rack
- 95 Fit for centering pins
- 96 Fit for centering

Modular storage rack CTS

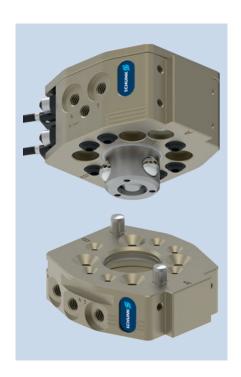


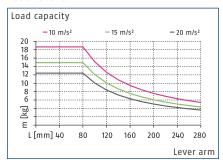
Tor detailed information, see the "CTS" chapter in the catalog, or visit schunk.com.

Optional modules COS

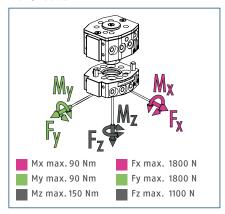


For detailed information, see the "COS" chapter in the catalog, or visit schunk.com.





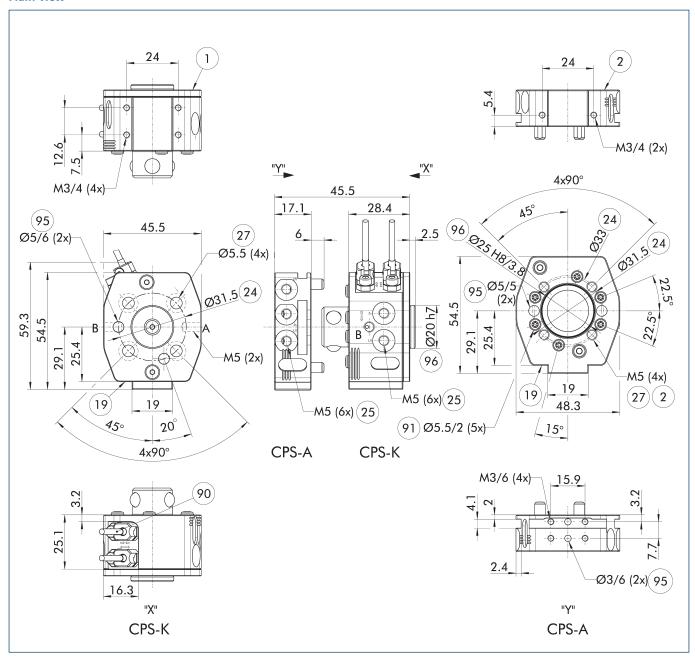
Max. loads



① This is the sum of all static loads that are permitted to act on the tool changer.

Description		CPS 007-K-S	CPS 007-K	CPS 007-A
		Change head	Change head	Tool
ID		1613262	1591016	1591017
Lock sensing		integrated	prepared	
Locking force	[N]	980	980	
Locking force provided by spring force	[N]	28	28	
Repeat accuracy	[mm]	0.015	0.015	
Weight	[kg]	0.19	0.19	0.08
Max. distance when locking	[mm]	1.5	1.5	
Number of pneumatic feed-throughs		6x M5	6x M5	6x M5
Lock/unlock main connection		M5	M5	
Max. permissible XY axis offset	[mm]	±1	±1	±1
Max. permissible angular offset XY	[°]	±0.8	±0.8	±0.8
Max. permissible angular offset Z	[°]	±2	±2	±2
Robot-side connection		ISO 9409-1-31.5-4-M5	ISO 9409-1-31.5-4-M5	
Tool-side connection				ISO 9409-1-31.5-4-M5
Min./max. ambient temperature	[°C]	5/60	5/60	5/60
Min./max. operating pressure	[bar]	4.517	4.517	4.517
Screw connection diagram		\$7	\$7	\$7
Opening/closing time	[s]	0.1/0.1	0.1/0.1	
Cylinder volume per double stroke	[cm³]	7.1	7.1	
Max. volumetric flow per pneumatic feed-through		150 I/min (M5)	150 I/min (M5)	150 I/min (M5)
Max. dynamic moment Mx	[Nm]	30	30	30
Max. dynamic moment My	[Nm]	30	30	30
Max. dynamic moment Mz	[Nm]	50	50	50
Force Fx max. dynamic	[N]	600	600	600
Force Fy max. dynamic	[N]	600	600	600
Force Fz max. dynamic	[N]	370	370	370

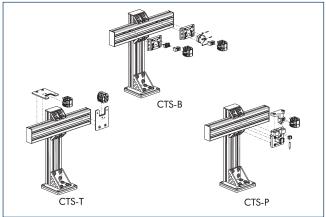
Main view



The drawing shows the basic version of the tool changer without taking account of the dimensions of the options described below.

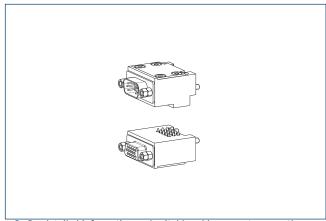
- A, a Air connection locked
- B, b Air connection unlocked
- (1) Robot-side connection
- (2) Tool-side connection
- (19) Mounting surface for options
- 24) Bolt circle
- 25) Pneumatic feed-throughs
- 27 Through holes for screw connections
- Attachmient kit for lock/unlock monitoring (bracket and sensor)
- (91) Axial air connection (supplied with locking screw)
- 95 Fit for centering pins
- 96 Fit for centering

Modular storage rack CTS



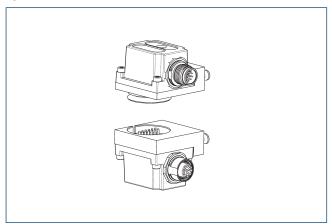
Tor detailed information, see the "CTS" chapter in the catalog, or visit schunk.com.

Optional modules COS



 For detailed information and suitable cable connectors, see the "COS" chapter in the catalog, or visit schunk.com.

Optional modules COB

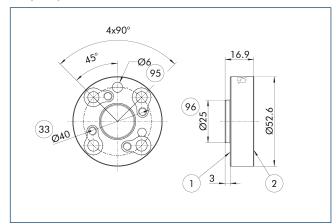


An adapter plate is required to mount COB option modules on CPS tool changers.

Description	ID	Screw connection diagram
Adapter plate		
COS Z84-A-S7/B	1618198	\$7
COS Z84-K-S7/B	1618197	S7

Tor detailed information and suitable cable connectors, see the "COB" chapter in the catalog, or visit schunk.com.

Adapter plate ISO-A40-R

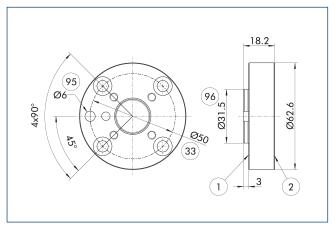


- 1 Robot-side connection
- 2 Tool-side connection
- 33 DIN ISO-9409 bolt circle
- 95) Fit for centering pins
- 96) Fit for centering

Robot side adapter plate

Description	ID
Adapter plate	
A-ISO040/CPS007	1581604

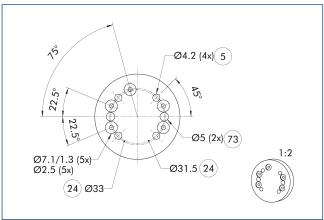
Adapter plate ISO-A50-R



- 1 Robot-side connection
- 2 Tool-side connection
- 33) DIN ISO-9409 bolt circle
- Robot side adapter plate
- 95 Fit for centering pins
- 96) Fit for centering

Description	ID
Adapter plate	
A-IS0050/CPS007	1581606

Design of an adapter plate for using the axial air feed-through



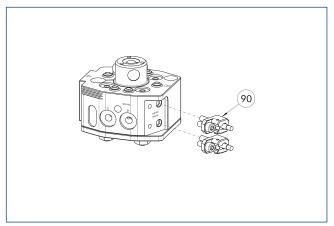
(5) Through hole for connection with screws

24) Bolt circle

73) Fit for centering pins

The adapter plate serves as an interface between the change adapter and the tool of the customer. To ensure correct use of the axial air feed-throughs, the counterbores shown in the drawing must be taken into account when designing the adapter plate. The appropriate seals are included in the accessory kit.

Assembly situation of the locking monitoring



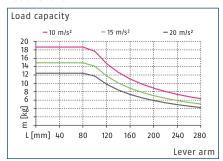
 Attachmient kit for lock/unlock monitoring (bracket and sensor)

The drawing shows the installation situation with the prepared locking monitoring.

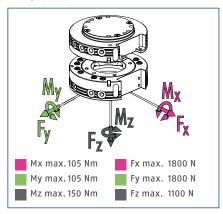
De	escription	ID
At	tachment kit for pr	oximity switch
AS	S-CPS-007	1610158

The K-S variants of the CPS-K already have lock monitoring integrated, so there is no need to order an additional attachment kit. The scope of delivery of each attachment kit contains one preset sensor with bracket, meaning that two attachment kits are required per CPS-K.





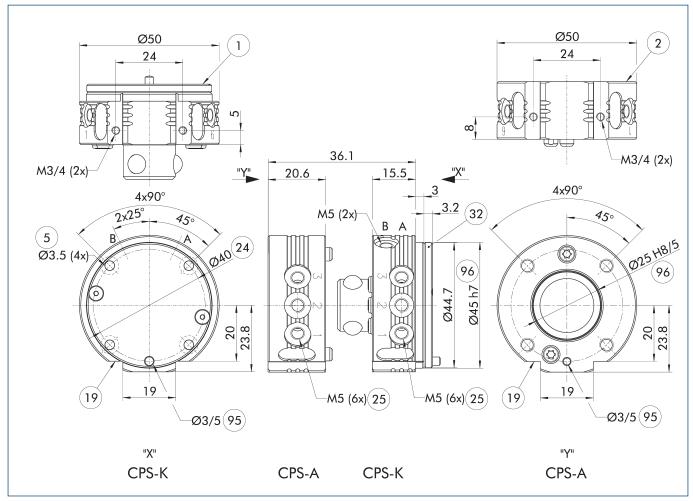
Max. loads



① This is the sum of all static loads that are permitted to act on the tool changer.

Description		CPS 011-K	CPS 011-A
		Change head	Tool
ID		1619555	1619558
Lock sensing		optional	
Locking force	[N]	1100	
Locking force provided by spring force	[N]	23	
Repeat accuracy	[mm]	0.015	
Weight	[kg]	0.13	0.08
Max. distance when locking	[mm]	1.5	
Number of pneumatic feed-throughs		6x M5	6x M5
Lock/unlock main connection		M5	
Max. permissible XY axis offset	[mm]	±1	±1
Max. permissible angular offset XY	[°]	±0.8	±0.8
Max. permissible angular offset Z	[°]	±2	±2
Min./max. ambient temperature	[°C]	5/60	5/60
Min./max. operating pressure	[bar]	4.5/7	4.517
Screw connection diagram		S7	\$7
Opening/closing time	[s]	0.1/0.1	
Cylinder volume per double stroke	[cm³]	7.9	
Max. volumetric flow per pneumatic feed-through		150 I/min (M5)	150 I/min (M5)
Max. dynamic moment Mx	[Nm]	35	35
Max. dynamic moment My	[Nm]	35	35
Max. dynamic moment Mz	[Nm]	50	50
Force Fx max. dynamic	[N]	600	600
Force Fy max. dynamic	[N]	600	600
Force Fz max. dynamic	[N]	370	370

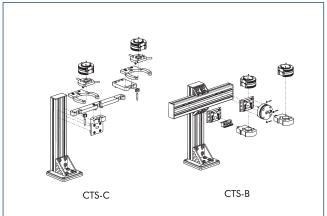
Main view



The drawing shows the basic version of the tool changer without taking account of the dimensions of the options described below.

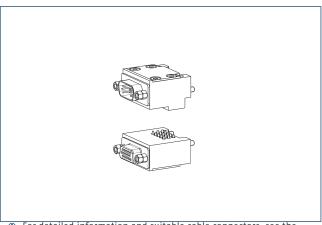
- The robot-side plate mounted on the CPS-K is a cover for the piston chamber. It is essential that it is supported by the adapter plate. See the further product information for a note on how to design this adapter plate.
- A, a Air connection locked
- B, b Air connection unlocked
- (1) Robot-side connection
- 2 Tool-side connection
- (5) Through hole for connection with screws
- 19 Mounting surface for options
- 24) Bolt circle
- 25) Pneumatic feed-throughs
- 32 Cover
- 95) Fit for centering pins
- 96 Fit for centering

Modular storage rack CTS



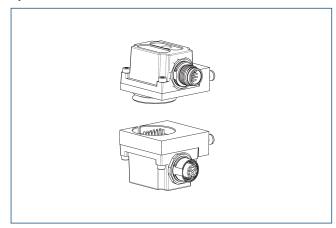
 For detailed information, see the "CTS" chapter in the catalog, or visit schunk.com.

Optional modules COS



 For detailed information and suitable cable connectors, see the "COS" chapter in the catalog, or visit schunk.com.

Optional modules COB

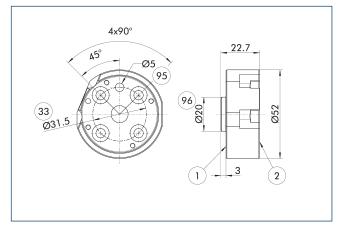


An adapter plate is required to mount COB option modules on CPS tool changers.

Description	ID	Screw connection diagram
Adapter plate		
COS Z84-A-S7/B	1618198	\$7
COS Z84-K-S7/B	1618197	\$7

① For detailed information and suitable cable connectors, see the "COB" chapter in the catalog, or visit schunk.com.

Adapter plate ISO-A31.5-R

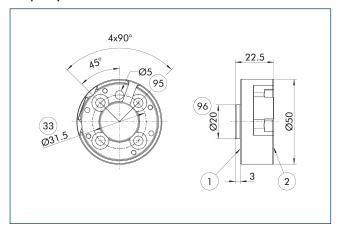


- 1 Robot-side connection
- 95 Fit for centering pins
- 2 Tool-side connection
- 96 Fit for centering
- 33 DIN ISO-9409 bolt circle

Robot side adapter plate

Description	ID
Adapter plate	
A-ISO031/CPS011	1581616

Adapter plate ISO-A31.5-SIP-R

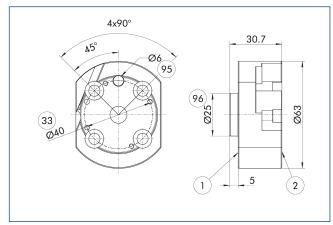


- 1 Robot-side connection
- 95 Fit for centering pins
- (2) Tool-side connection
- 96) Fit for centering
- 33 DIN ISO-9409 bolt circle

Robot side adapter plate

Description	ID
Adapter plate	
A-ISO031/CPS011-SIP	1581623

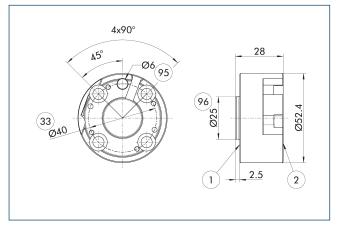
Adapter plate ISO-A40-R



- 1 Robot-side connection
- 2 Tool-side connection
- 33 DIN ISO-9409 bolt circle
- 95 Fit for centering pins 96 Fit for centering
- Robot side adapter plate

Description	ID
Adapter plate	
A-IS0040/CPS011	1581629

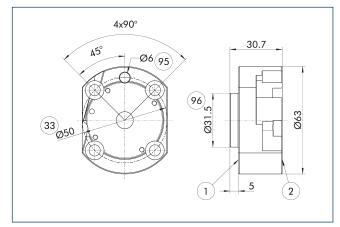
Adapter plate ISO-A40-SIP-R



- 1 Robot-side connection
- 2 Tool-side connection
- 33 DIN ISO-9409 bolt circle
- Robot side adapter plate
- 95) Fit for centering pins
- 96 Fit for centering

Description	ID
Adapter plate	
Λ=ISOO/(O/CDSO11=SID	15816/18

Adapter plate ISO-A50-R

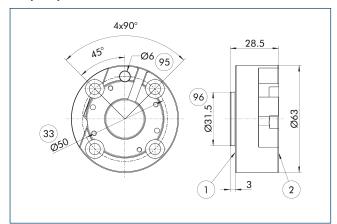


- 1 Robot-side connection
- 2 Tool-side connection
- 33 DIN ISO-9409 bolt circle
- 95 Fit for centering pins
- 96 Fit for centering

Robot side adapter plate

Description	ID
Adapter plate	1.5
Adapter plate	
Δ-IS0050/CPS011	1581654

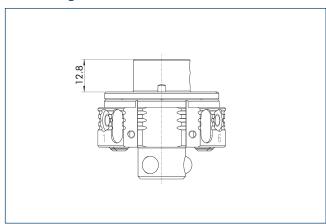
Adapter plate ISO-A50-SIP-R



- 1) Robot-side connection
- 2 Tool-side connection
- 33 DIN ISO-9409 bolt circle
- 95) Fit for centering pins
- 96) Fit for centering

Robot side adapter pla	te	
Description	ID	
Adapter plate		
A-ISO050/CPS011-SIP	1581659	

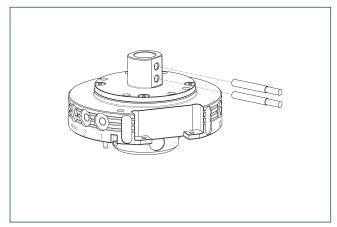
Lock sensing



The drawing shows the minimum height of the adapter plate required for installing locking monitoring.

Description	ID
Lock sensing	
AS-CPS-011-SIP-IN00	1596403

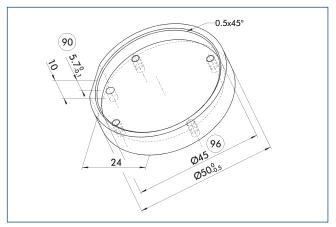
Lock sensing



Description	ID	Often combined
Inductive proximity switch		
IN 41-S-M8-PNP	1325755	
Connection cables		
KA BG08-L 3P-0300-PNP	0301622	•
KA BG08-L 3P-0500-PNP	0301623	
KA BW08-L 3P-0300-PNP	0301594	
KA BW08-L 3P-0500-PNP	0301502	
Clip for connector/socket		
CLI-M8	0301463	

Per unit two sensors (closer/S) are required for each unit, as well as extension cables on option. Please consider the minimum permissible bending radii for sensor cables. These are generally 35 mm.

Adapter plate design

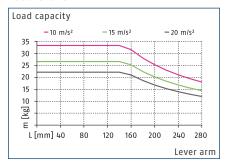


Recommended adapter plate depth

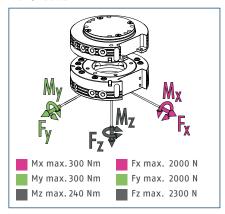
96 Fit for centering

Recommendation for the design of the adapter plate.





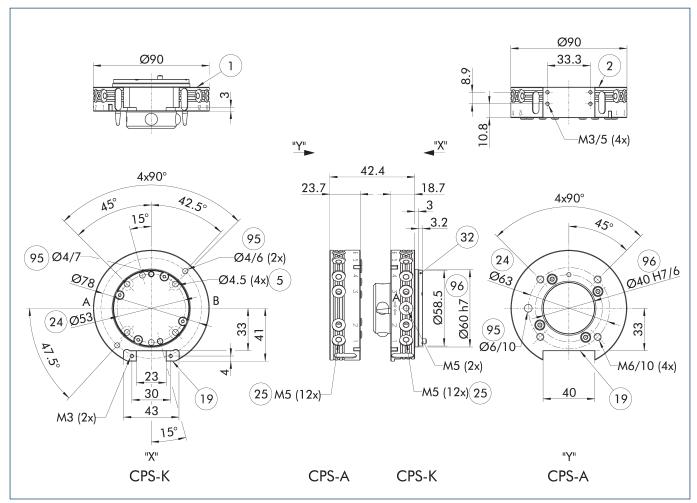
Max. loads



① This is the sum of all static loads that are permitted to act on the tool changer.

Description		CPS 020-K	CPS 020-A
Description		Change head	Tool
ID		1591033	1591034
Lock sensing		optional	1351034
Locking force	[N]	2300	
Locking force provided by spring force	[N]	68	
Repeat accuracy	[mm]	0.015	
Weight	[kg]	0.48	0.35
Max. distance when locking	[mm]	2	
Number of pneumatic feed-throughs		12x M5	12x M5
Lock/unlock main connection		M5	
Max. permissible XY axis offset	[mm]	±1	±1
Max. permissible angular offset XY	[°]	±0.8	±0.8
Max. permissible angular offset Z	[°]	±2	±2
Min./max. ambient temperature	[°C]	5/60	5/60
Min./max. operating pressure	[bar]	4.5/7	4.5/7
Screw connection diagram		K	K
Opening/closing time	[s]	0.1/0.1	
Cylinder volume per double stroke	[cm³]	20	
Max. volumetric flow per pneumatic feed-through		150 I/min (M5)	150 I/min (M5)
Max. dynamic moment Mx	[Nm]	100	100
Max. dynamic moment My	[Nm]	100	100
Max. dynamic moment Mz	[Nm]	80	80
Force Fx max. dynamic	[N]	660	660
Force Fy max. dynamic	[N]	660	660
Force Fz max. dynamic	[N]	760	760

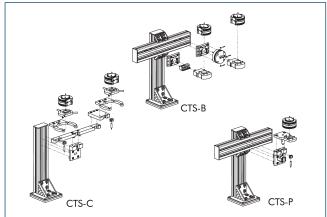
Main view



The drawing shows the basic version of the tool changer without taking account of the dimensions of the options described below.

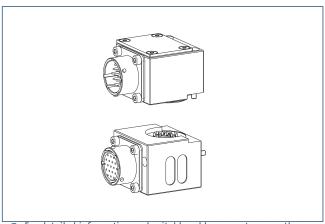
- The robot-side plate mounted on the CPS-K is a cover for the piston chamber. It is essential that it is supported by the adapter plate. See the further product information for a note on how to design this adapter plate.
- A, a Air connection locked
- B, b Air connection unlocked
- (1) Robot-side connection
- (2) Tool-side connection
- (5) Through hole for connection with screws
- 19 Mounting surface for options
- 24) Bolt circle
- 25) Pneumatic feed-throughs
- 32 Cover
- 95) Fit for centering pins
- 96 Fit for centering

Modular storage rack CTS



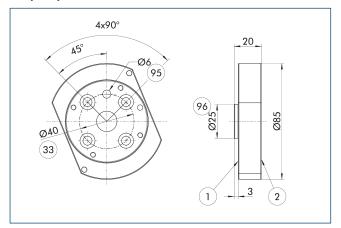
Tor detailed information, see the "CTS" chapter in the catalog, or visit schunk.com.

Optional modules COS



Tor detailed information and suitable cable connectors, see the "COS" chapter in the catalog, or visit schunk.com.

Adapter plate ISO-A40-R



- 1 Robot-side connection
- 2 Tool-side connection
- 33 DIN ISO-9409 bolt circle

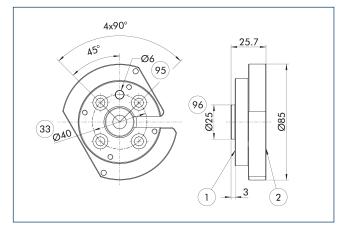
Robot side adapter plate

95 Fi	t for	centering	pins
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96 Fit for centering

Description	ID
Adapter plate	
A-IS0040/CPS020-021	1581668

Adapter plate ISO-A40-SIP-R

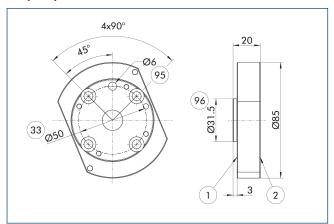


- 1 Robot-side connection
- 2 Tool-side connection
- 33 DIN ISO-9409 bolt circle
- 95 Fit for centering pins
- 96 Fit for centering

Robot side adapter plate

Description	ID	
Adapter plate		
A-ISO040/CPS020-021-SIP	1581676	

Adapter plate ISO-A50-R

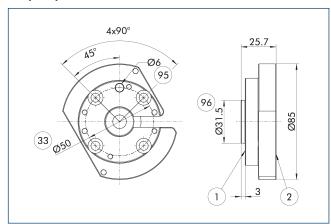


- 1) Robot-side connection
- (2) Tool-side connection
- 33 DIN ISO-9409 bolt circle
- 95) Fit for centering pins
- 96) Fit for centering

Robot side adapter plate

Description	ID
Adapter plate	
A-IS0050/CPS020-021	1581683

Adapter plate ISO-A50-SIP-R

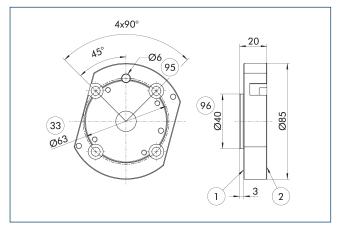


- 1) Robot-side connection
- (2) Tool-side connection
- 33 DIN ISO-9409 bolt circle
- 95) Fit for centering pins
- 96) Fit for centering

Robot side adapter plate

Description	ID	
Adapter plate		
A-ISO050/CPS020-021-SIP	1581686	

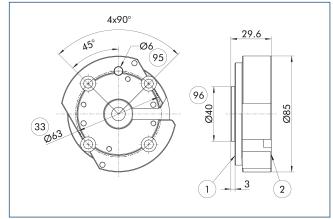
Adapter plate ISO-A63-R



- 1 Robot-side connection
- 2 Tool-side connection
- 33 DIN ISO-9409 bolt circle
- Robot side adapter plate
- 95 Fit for centering pins
- 96 Fit for centering

Description	ID	
Adapter plate		
A-ISO063/CPS020-021	1581689	

Adapter plate ISO-A63-SIP-R

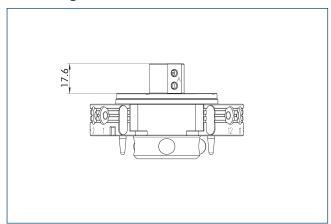


- 1 Robot-side connection
- 2 Tool-side connection
- 33 DIN ISO-9409 bolt circle
- 95 Fit for centering pins
- 96 Fit for centering

Robot side adapter plate

Description	ID	
Adapter plate		
A-ISO063/CPS020-021-SIP	1581694	

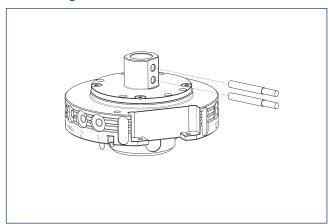
Lock sensing



The drawing shows the minimum height of the adapter plate required for installing locking monitoring.

Description	ID
Lock sensing	
AS-CPS-020-SIP-IN00	1596404

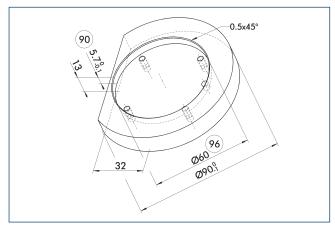
Lock sensing



Description	ID	Often combined
Inductive proximity switch		
IN 41-S-M8-PNP	1325755	
Connection cables		
KA BG08-L 3P-0300-PNP	0301622	•
KA BG08-L 3P-0500-PNP	0301623	
KA BW08-L 3P-0300-PNP	0301594	
KA BW08-L 3P-0500-PNP	0301502	
Clip for connector/socket		
CLI-M8	0301463	

Per unit two sensors (closer/S) are required for each unit, as well as extension cables on option. Please consider the minimum permissible bending radii for sensor cables. These are generally 35 mm.

Adapter plate design

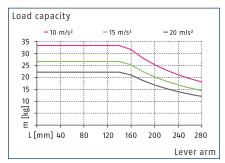


90 Recommended adapter plate depth

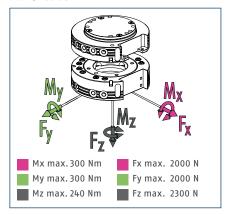
96 Fit for centering

Recommendation for the design of the adapter plate.





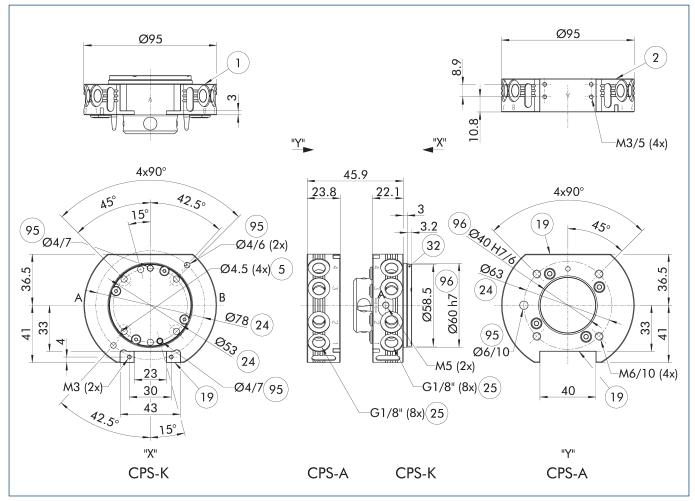
Max. loads



① This is the sum of all static loads that are permitted to act on the tool changer.

Description		CPS 021-K	CPS 021-A
		Change head	Tool
ID		1619570	1619572
Lock sensing		optional	
Locking force	[N]	2300	
Locking force provided by spring force	[N]	68	
Repeat accuracy	[mm]	0.015	
Weight	[kg]	0.51	0.35
Max. distance when locking	[mm]	2	
Number of pneumatic feed-throughs		8x G1/8"	8x G1/8"
Lock/unlock main connection		M5	
Max. permissible XY axis offset	[mm]	±1	±1
Max. permissible angular offset XY	[°]	±0.8	±0.8
Max. permissible angular offset Z	[°]	±2	±2
Min./max. ambient temperature	[°C]	5/60	5/60
Min./max. operating pressure	[bar]	4.5/7	4.5/7
Screw connection diagram		K side A/K J via adapter plate side B	K side A/K J via adapter plate side B
Opening/closing time	[s]	0.1/0.1	
Cylinder volume per double stroke	[cm³]	24	
Max. volumetric flow per pneumatic feed-through		650 I/min (G1/8")	650 I/min (G1/8")
Max. dynamic moment Mx	[Nm]	100	100
Max. dynamic moment My	[Nm]	100	100
Max. dynamic moment Mz	[Nm]	80	80
Force Fx max. dynamic	[N]	660	660
Force Fy max. dynamic	[N]	660	660
Force Fz max. dynamic	[N]	760	760

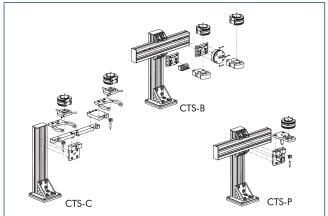
Main view



The drawing shows the basic version of the tool changer without taking account of the dimensions of the options described below.

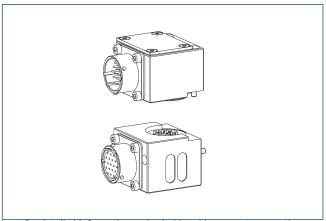
- The robot-side plate mounted on the CPS-K is a cover for the piston chamber. It is essential that it is supported by the adapter plate. See the further product information for a note on how to design this adapter plate.
- A, a Air connection locked
- B, b Air connection unlocked
- (1) Robot-side connection
- 2 Tool-side connection
- (5) Through hole for connection with screws
- 19 Mounting surface for options
- 24) Bolt circle
- 25) Pneumatic feed-throughs
- 32 Cover
- 95) Fit for centering pins
- 96 Fit for centering

Modular storage rack CTS



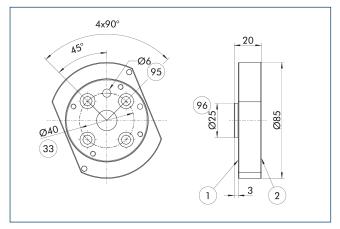
Tor detailed information, see the "CTS" chapter in the catalog, or visit schunk.com.

Optional modules COS



 For detailed information and suitable cable connectors, see the "COS" chapter in the catalog, or visit schunk.com.

Adapter plate ISO-A40-R

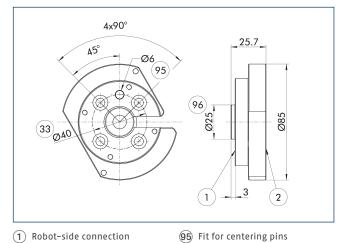


- 1 Robot-side connection
- 2 Tool-side connection
- 33 DIN ISO-9409 bolt circle
- 95) Fit for centering pins
- 96 Fit for centering

Robot side adapter plate

Description	ID
Adapter plate	
A-IS0040/CPS020-021	1581668

Adapter plate ISO-A40-SIP-R

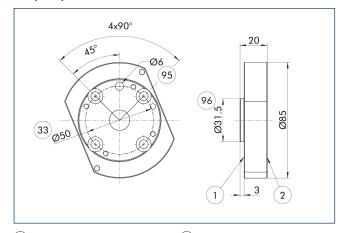


- 1 Robot-side connection
- 2 Tool-side connection
- 33 DIN ISO-9409 bolt circle
- 96 Fit for centering

Robot side adapter plate

Description	ID	
Adapter plate		
A-ISO040/CPS020-021-SIP	1581676	

Adapter plate ISO-A50-R

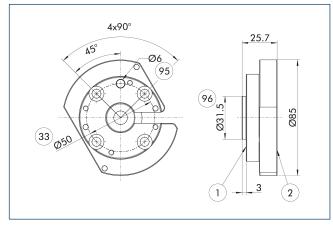


- 1) Robot-side connection
- (2) Tool-side connection
- 33 DIN ISO-9409 bolt circle
- 95) Fit for centering pins
- 96) Fit for centering

Robot side adapter plate

Description	ID
Adapter plate	
A-IS0050/CPS020-021	1581683

Adapter plate ISO-A50-SIP-R

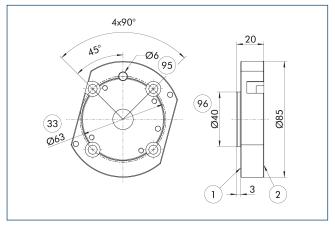


- 1) Robot-side connection
- (2) Tool-side connection
- 33 DIN ISO-9409 bolt circle
- 95) Fit for centering pins
- 96) Fit for centering

Robot side adapter plate

Description	ID	
Adapter plate		
A-IS0050/CPS020-021-SIP	1581686	

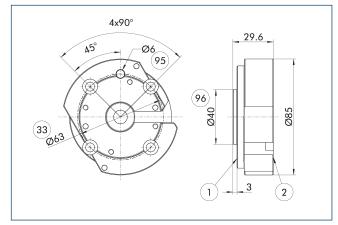
Adapter plate ISO-A63-R



- 1 Robot-side connection
- 2 Tool-side connection
- 33 DIN ISO-9409 bolt circle
- Robot side adapter plate
- 95) Fit for centering pins
- 96 Fit for centering

Description	ID
Adapter plate	
A-IS0063/CPS020-021	1581689

Adapter plate ISO-A63-SIP-R

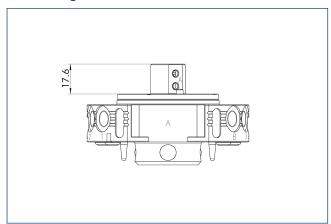


- 1 Robot-side connection
- 2 Tool-side connection
- 33 DIN ISO-9409 bolt circle
- 95 Fit for centering pins
- 96 Fit for centering

Robot side adapter plate

Description	ID	
Adapter plate		
A-IS0063/CPS020-021-SIP	1581694	

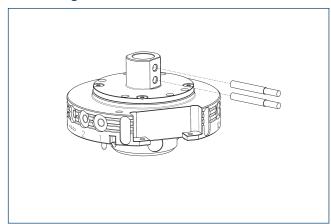
Lock sensing



The drawing shows the minimum height of the adapter plate required for installing locking monitoring.

Description	ID
Lock sensing	
AS-CPS-021-SIP-IN00	1596406

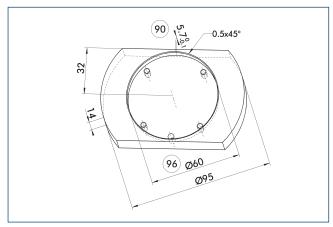
Lock sensing



Description	ID	Often combined
Inductive proximity switch		
IN 41-S-M8-PNP	1325755	
Connection cables		
KA BG08-L 3P-0300-PNP	0301622	•
KA BG08-L 3P-0500-PNP	0301623	
KA BW08-L 3P-0300-PNP	0301594	
KA BW08-L 3P-0500-PNP	0301502	
Clip for connector/socket		
CLI-M8	0301463	

(i) Per unit two sensors (closer/S) are required for each unit, as well as extension cables on option. Please consider the minimum permissible bending radii for sensor cables. These are generally 35 mm.

Adapter plate design

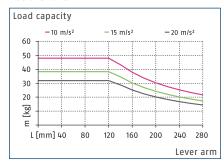


90 Recommended adapter plate depth

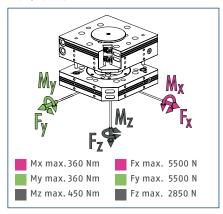
96 Fit for centering

Recommendation for the design of the adapter plate.





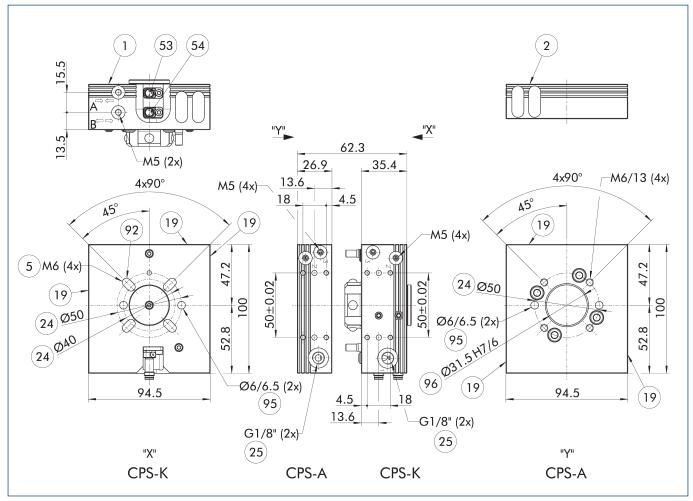
Max. loads



① This is the sum of all static loads that are permitted to act on the tool changer.

Description		CPS 029-K-S	CPS 029-K	CPS 029-A
		Change head	Change head	Tool
D		1613280	1590976	1590977
Lock sensing		integrated	prepared	
ocking force	[N]	2900	2900	
ocking force provided by spring force	[N]	24	24	
Repeat accuracy	[mm]	0.015	0.015	
Neight	[kg]	1	1	0.7
Max. distance when locking	[mm]	1.5	1.5	
Number of pneumatic Feed-throughs		2x G1/8"	2x G1/8"	2x G1/8"
Number of pneumatic Feed-throughs		4x M5	4x M5	4x M5
Lock/unlock main connection		M5	M5	
Max. permissible XY axis offset	[mm]	±1	±1	±1
Max. permissible angular offset XY	[°]	±0.8	±0.8	±0.8
Max. permissible angular offset Z	[°]	±1	±1	±1
Robot-side connection		ISO 9409-1-50-4-M6	ISO 9409-1-50-4-M6	
Tool-side connection				ISO 9409-1-50-4-M6
Min./max. ambient temperature	[°C]	5/60	5/60	5/60
Min./max. operating pressure	[bar]	4.5/7	4.5/7	4.5/7
Screw connection diagram		3 x J	3 x J	3 x J
Opening/closing time	[s]	0.1/0.1	0.1/0.1	
Cylinder volume per double stroke	[cm³]	15	15	
Max. volumetric flow per pneumatic feed-through		650 I/min (G1/8")	650 I/min (G1/8")	650 I/min (G1/8")
Max. volumetric flow per pneumatic feed-through		150 I/min (M5)	150 I/min (M5)	150 I/min (M5)
Max. dynamic moment Mx	[Nm]	120	120	120
Max. dynamic moment My	[Nm]	120	120	120
Max. dynamic moment Mz	[Nm]	150	150	150
Force Fx max. dynamic	[N]	1850	1850	1850
Force Fy max. dynamic	[N]	1850	1850	1850
Force Fz max. dynamic	[N]	950	950	950

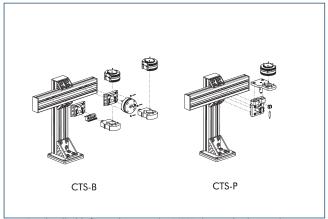
Main view



The drawing shows the basic version of the tool changer without taking account of the dimensions of the options described below.

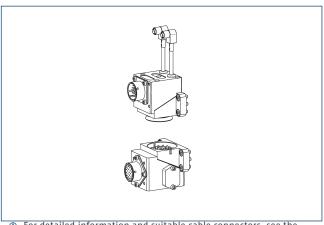
- A, a Air connection locked
- B, b Air connection unlocked
- (1) Robot-side connection
- 2 Tool-side connection
- (5) Through hole for connection with screws
- (19) Mounting surface for options
- 24) Bolt circle
- 25) Pneumatic feed-throughs
- (53) Monitoring Position unlocked
- (54) Monitoring Position locked
- 95) Fit for centering pins
- 96 Fit for centering

Modular storage rack CTS



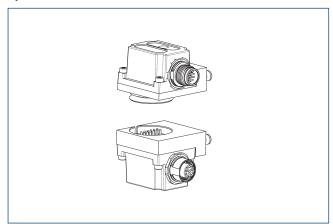
Tor detailed information, see the "CTS" chapter in the catalog, or visit schunk.com.

Optional modules COS



For detailed information and suitable cable connectors, see the "COS" chapter in the catalog, or visit schunk.com.

Optional modules COB

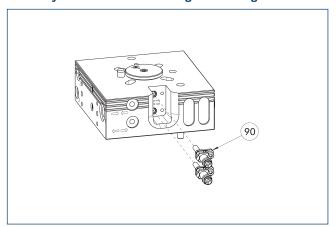


An adapter plate is required to mount COB option modules on CPS tool changers. $% \label{eq:condition}%$

Description	ID	Screw connection diagram
Adapter plate		
COS Z83-J/B	1610155	J

Tor detailed information and suitable cable connectors, see the "COB" chapter in the catalog, or visit schunk.com.

Assembly situation of the locking monitoring



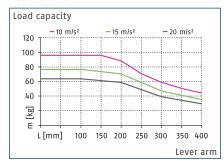
Attachmient kit for lock/unlock monitoring (bracket and sensor)

The drawing shows the installation situation with the prepared locking monitoring.

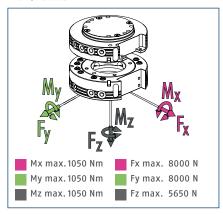
Description	ID
Attachment kit for pr	oximity switch
AS-CPS-029	1622613

The K-S variants of the CPS-K already have lock monitoring integrated, so there is no need to order an additional attachment kit. The scope of delivery of each attachment kit contains one preset sensor with bracket, meaning that two attachment kits are required per CPS-K.





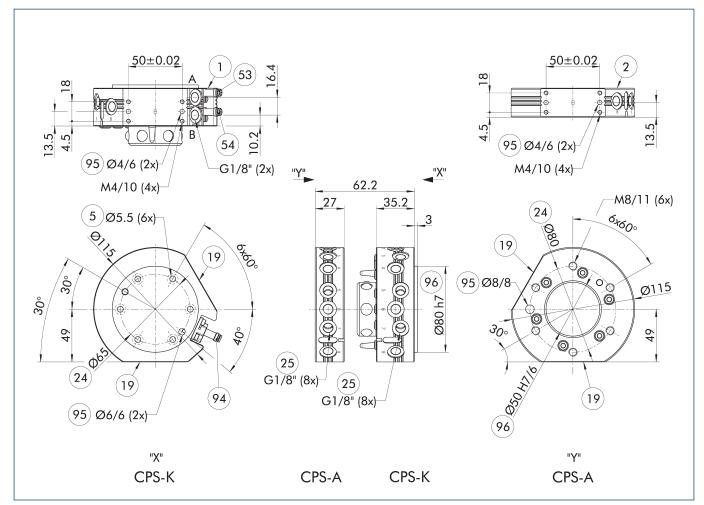
Max. loads



① This is the sum of all static loads that are permitted to act on the tool changer.

Description		CPS 040-K-S	CPS 040-K	CPS 040-A
		Change head	Change head	Tool
ID		1613282	1590978	1590979
Lock sensing		integrated	prepared	
Locking force	[N]	5600	5600	
Locking force provided by spring force	[N]	91	91	
Repeat accuracy	[mm]	0.015	0.015	
Weight	[kg]	1.1	1.1	0.62
Max. distance when locking	[mm]	3	3	
Number of pneumatic feed-throughs		8x G1/8"	8x G1/8"	8x G1/8"
Lock/unlock main connection		G1/8"	G1/8"	
Max. permissible XY axis offset	[mm]	±2	±2	±2
Max. permissible angular offset XY	[°]	±1	±1	±1
Max. permissible angular offset Z	[°]	±2	±2	±2
Min./max. ambient temperature	[°C]	5/60	5/60	5/60
Min./max. operating pressure	[bar]	4.5/7	4.5/7	4.5/7
Screw connection diagram		2 x J	2 x J	2 x J
Opening/closing time	[s]	0.1/0.1	0.1/0.1	
Cylinder volume per double stroke	[cm³]	42	42	
Max. volumetric flow per pneumatic feed-through		650 I/min (G1/8")	650 I/min (G1/8")	650 I/min (G1/8")
Max. dynamic moment Mx	[Nm]	350	350	350
Max. dynamic moment My	[Nm]	350	350	350
Max. dynamic moment Mz	[Nm]	350	350	350
Force Fx max. dynamic	[N]	2700	2700	2700
Force Fy max. dynamic	[N]	2700	2700	2700
Force Fz max. dynamic	[N]	1900	1900	1900

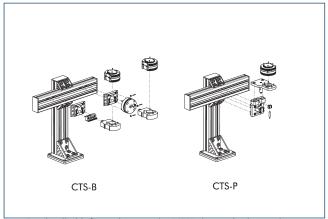
Main view CPS 040



The drawing shows the basic version of the tool changer without taking account of the dimensions of the options described below.

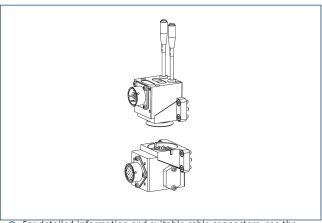
- A, a Air connection locked
- B, b Air connection unlocked
- (1) Robot-side connection
- 2 Tool-side connection
- (5) Through hole for connection with screws
- (19) Mounting surface for options
- 24) Bolt circle
- 25) Pneumatic feed-throughs
- (53) Monitoring Position unlocked
- (54) Monitoring Position locked
- 95) Fit for centering pins
- 96 Fit for centering

Modular storage rack CTS



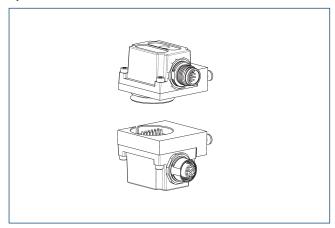
Tor detailed information, see the "CTS" chapter in the catalog, or visit schunk.com.

Optional modules COS



Tor detailed information and suitable cable connectors, see the "COS" chapter in the catalog, or visit schunk.com.

Optional modules COB

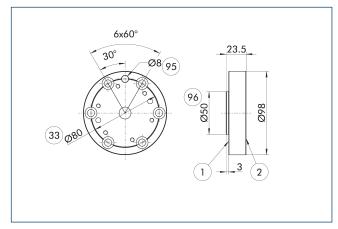


An adapter plate is required to mount COB option modules on CPS tool changers.

Description	ID	Screw connection diagram
Adapter plate		
COS Z83-J/B	1610155	J

Tor detailed information and suitable cable connectors, see the "COB" chapter in the catalog, or visit schunk.com.

Adapter plate ISO-A80-R

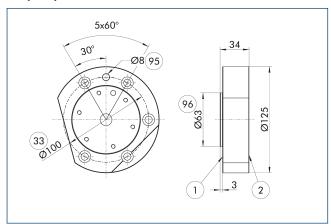


- 1 Robot-side connection
- 95 Fit for centering pins
- 2 Tool-side connection
- **96** Fit for centering
- 33 DIN ISO-9409 bolt circle

Robot side adapter plate

Description	ID
Adapter plate	
A-IS0080/CPS040	1581814

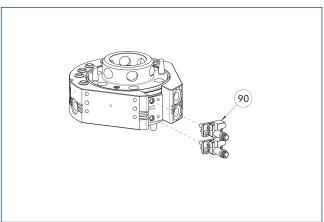
Adapter plate ISO-A100-R



- 1 Robot-side connection
- 95 Fit for centering pins
- 2 Tool-side connection33 DIN ISO-9409 bolt circle
- 96 Fit for centering
- Robot side adapter plate

Description	ID
Adapter plate	
A-IS0100/CPS040	1581811

Assembly situation of the locking monitoring



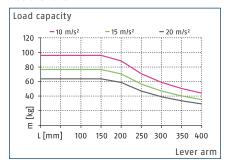
Attachmient kit for lock/unlock monitoring (bracket and sensor)

The drawing shows the installation situation with the prepared locking monitoring.

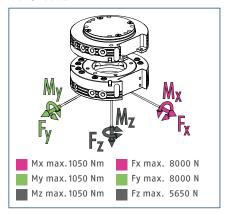
Description	ID
Attachment kit for p	oroximity swi
AS-CPS-040-076	1610160

The K-S variants of the CPS-K already have lock monitoring integrated, so there is no need to order an additional attachment kit. The scope of delivery of each attachment kit contains one preset sensor with bracket, meaning that two attachment kits are required per CPS-K.



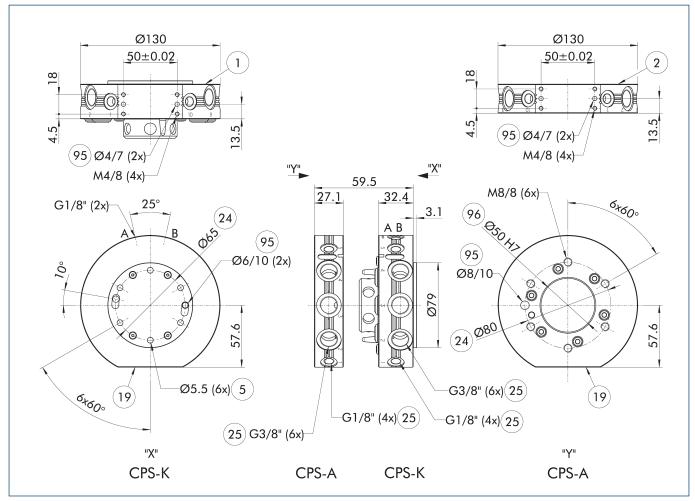


Max. loads



① This is the sum of all static loads that are permitted to act on the tool changer.

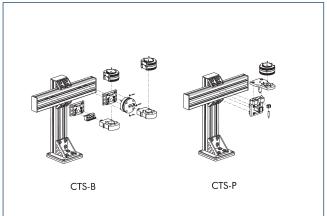
Description		CPS 041-K	CPS 041-A
		Change head	Tool
D		1619573	1619574
Lock sensing		optional	
Locking force	[N]	5600	
Locking force provided by spring force	[N]	47	
Repeat accuracy	[mm]	0.015	
Weight	[kg]	1.4	0.8
Max. distance when locking	[mm]	3	
Number of pneumatic feed-throughs		6x G3/8"	6x G3/8"
Number of pneumatic feed-throughs		4x G1/8"	4x G1/8"
Lock/unlock main connection		G1/8"	
Max. permissible XY axis offset	[mm]	±2	±2
Max. permissible angular offset XY	[°]	±1	±1
Max. permissible angular offset Z	[°]	±2	±2
Min./max. ambient temperature	[°C]	5/60	5/60
Min./max. operating pressure	[bar]	4.5/7	4.517
Screw connection diagram		J	J
Opening/closing time	[s]	0.1/0.1	
Cylinder volume per double stroke	[cm³]	46	
Max. volumetric flow per pneumatic feed-through		1.400 I/min (G3/8")	1.400 l/min (G3/8")
Max. volumetric flow per pneumatic feed-through		650 l/min (G1/8")	650 I/min (G1/8")
Max. dynamic moment Mx	[Nm]	350	350
Max. dynamic moment My	[Nm]	350	350
Max. dynamic moment Mz	[Nm]	350	350
Force Fx max. dynamic	[N]	2700	2700
Force Fy max. dynamic	[N]	2700	2700
Force Fz max. dynamic	[N]	1900	1900



The drawing shows the basic version of the tool changer without taking account of the dimensions of the options described below.

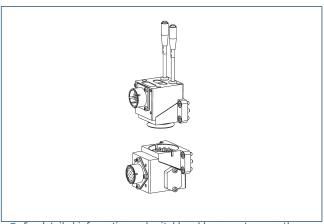
- The robot-side plate mounted on the CPS-K is a cover for the piston chamber. It is essential that it is supported by the adapter plate. See the further product information for a note on how to design this adapter plate.
- A, a Air connection locked
- B, b Air connection unlocked
- (1) Robot-side connection
- (2) Tool-side connection
- (5) Through hole for connection with screws
- 19 Mounting surface for options
- 24) Bolt circle
- 25) Pneumatic feed-throughs
- 32 Cover
- 95) Fit for centering pins
- 96 Fit for centering

Modular storage rack CTS



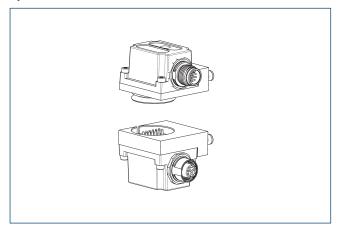
For detailed information, see the "CTS" chapter in the catalog, or visit schunk.com.

Optional modules COS



Tor detailed information and suitable cable connectors, see the "COS" chapter in the catalog, or visit schunk.com.

Optional modules COB

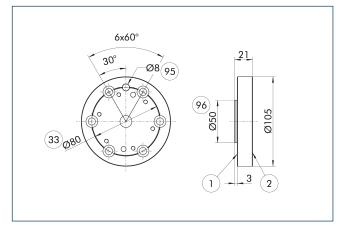


An adapter plate is required to mount COB option modules on CPS tool changers.

Description ID		Screw connection diagram
Adapter plate		
COS Z83-J/B	1610155	J

① For detailed information and suitable cable connectors, see the "COB" chapter in the catalog, or visit schunk.com.

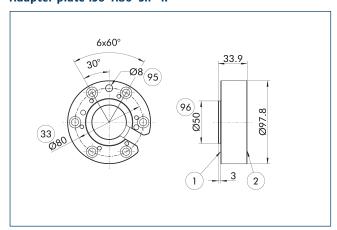
Adapter plate ISO-A80-R



- 1 Robot-side connection
- 2 Tool-side connection
- 33 DIN ISO-9409 bolt circle
- 95 Fit for centering pins
- 96 Fit for centering

Robot side adapter plate

Adapter plate ISO-A80-SIP-R

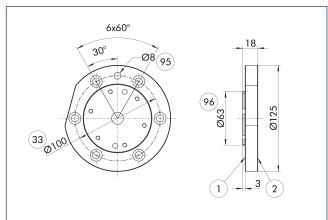


- 1) Robot-side connection
- (2) Tool-side connection
- 33 DIN ISO-9409 bolt circle
- 95) Fit for centering pins
- 96) Fit for centering

Robot side adapter plate

Description	ID
Adapter plate	
A-IS0080/CPS041-SIP	1581840

Adapter plate ISO-A100-R

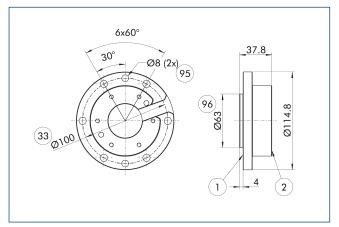


- 1) Robot-side connection
- (2) Tool-side connection
- 33 DIN ISO-9409 bolt circle
- 95) Fit for centering pins
- 96) Fit for centering

Robot side adapter plate

Description	ID
Adapter plate	
Δ-IS0100/CPS041	1581873

Adapter plate ISO-A100-SIP-R



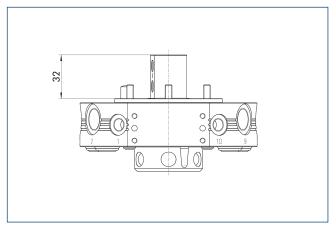
- 1 Robot-side connection
- 2 Tool-side connection
- 33 DIN ISO-9409 bolt circle

Robot side adapter plate

- 95) Fit for centering pins
- 96 Fit for centering

Description	ID
Adapter plate	
A-ISO100/CPS041-SIP	1581819

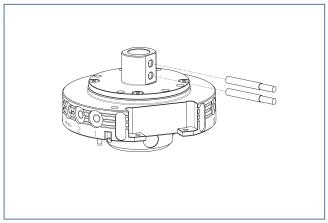
Lock sensing



The drawing shows the minimum height of the adapter plate required for installing locking monitoring.

Description	ID	
Lock sensing		
AS-CPS-041-SIP-IN00	1596409	

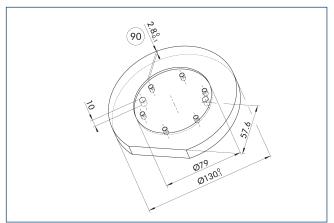
Lock sensing



Description	ID	Often combined
Inductive proximity switch		
IN 80-S-M12	0301578	
IN 80-S-M8	0301478	
INK 80-S	0301550	
Connection cables		
KA BG08-L 3P-0300-PNP	0301622	•
KA BG08-L 3P-0500-PNP	0301623	
KA BG12-L 3P-0500-PNP	30016369	
KA BW08-L 3P-0300-PNP	0301594	
KA BW08-L 3P-0500-PNP	0301502	
KA BW12-L 3P-0300-PNP	0301503	
KA BW12-L 3P-0500-PNP	0301507	
Clip for connector/socket		
CLI-M12	0301464	
CLI-M8	0301463	
Cable extension		
KV BG12-SG12 3P-0030-PNP	0301999	
KV BG12-SG12 3P-0060-PNP	0301998	
KV BW08-SG08 3P-0030-PNP	0301495	
KV BW08-SG08 3P-0100-PNP	0301496	
KV BW08-SG08 3P-0200-PNP	0301497	•
KV BW12-SG12 3P-0030-PNP	0301595	
KV BW12-SG12 3P-0100-PNP	0301596	
KV BW12-SG12 3P-0200-PNP	0301597	
Sensor distributor		
V2-M12	0301776	•
V2-M8	0301775	•
V4-M8	0301746	
V8-M8	0301751	

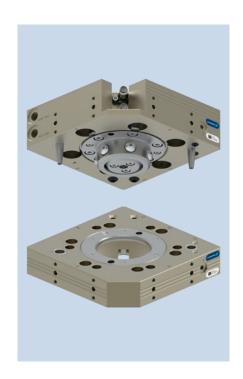
 Per unit two sensors (closer/S) are required for each unit, as well as extension cables on option. Please consider the minimum permissible bending radii for sensor cables. These are generally 35 mm.

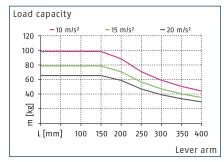
Adapter plate design



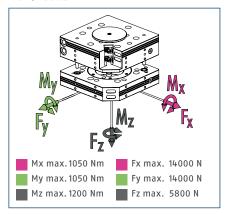
Recommended adapter plate depth

Recommendation for the design of the adapter plate.



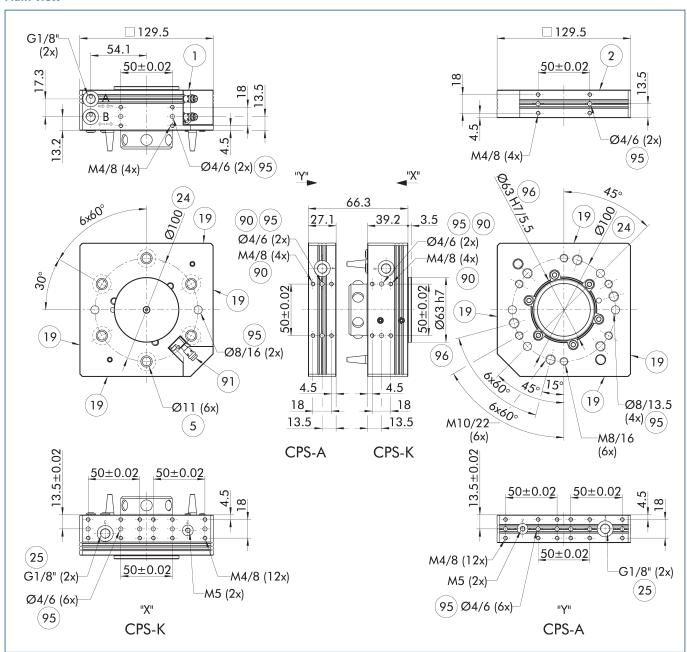


Max. loads



① This is the sum of all static loads that are permitted to act on the tool changer.

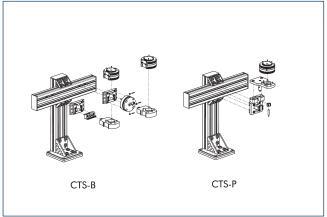
Description		CPS 046-K-S	CPS 046-K	CPS 046-A
		Change head	Change head	Tool
ID		1613284	1590984	1590986
Lock sensing		integrated	prepared	
Locking force	[N]	5800	5800	
Locking force provided by spring force	[N]	104	104	
Repeat accuracy	[mm]	0.015	0.015	
Weight	[kg]	2	2	1.1
Max. distance when locking	[mm]	2.5	2.5	
Number of pneumatic feed-throughs		2x G1/8"	2x G1/8"	2x G1/8"
Number of pneumatic feed-throughs		2x M5	2x M5	2x M5
Lock/unlock main connection		G1/8"	G1/8"	
Max. permissible XY axis offset	[mm]	±1.5	±1.5	±1.5
Max. permissible angular offset XY	[°]	±1	±1	±1
Max. permissible angular offset Z	[°]	±2	±2	±2
Robot-side connection		ISO 9409-1-100-6-M8	ISO 9409-1-100-6-M8	
Tool-side connection				ISO 9409-1-100-6-M8
Min./max. ambient temperature	[°C]	5/60	5/60	5/60
Min./max. operating pressure	[bar]	4.517	4.517	4.5/7
Screw connection diagram		5 x J	5 x J	5 x J
Opening/closing time	[s]	0.1/0.1		
Cylinder volume per double stroke	[cm³]	48		
Max. volumetric flow per pneumatic feed-through		650 I/min (G1/8")	650 I/min (G1/8")	650 I/min (G1/8")
Max. volumetric flow per pneumatic feed-through		150 I/min (M5)	150 I/min (M5)	150 I/min (M5)
Max. dynamic moment Mx	[Nm]	350	350	350
Max. dynamic moment My	[Nm]	350	350	350
Max. dynamic moment Mz	[Nm]	400	400	400
Force Fx max. dynamic	[N]	4600	4600	4600
Force Fy max. dynamic	[N]	4600	4600	4600
Force Fz max. dynamic	[N]	1950	1950	1950



The drawing shows the basic version of the tool changer without taking account of the dimensions of the options described below.

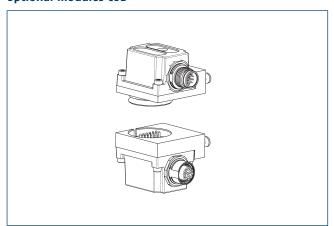
- A, a Air connection locked
- B, b Air connection unlocked
- (1) Robot-side connection
- (2) Tool-side connection
- (5) Through hole for connection with screws
- (19) Mounting surface for options
- 24) Bolt circle
- **25** Pneumatic feed-throughs
- 90 on both sides
- (91) Sensor connections for the lock monitoring
- 95) Fit for centering pins
- 96) Fit for centering

Modular storage rack CTS



Tor detailed information, see the "CTS" chapter in the catalog, or visit schunk.com.

Optional modules COB

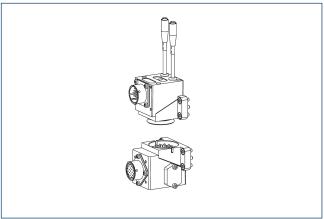


An adapter plate is required to mount COB option modules on CPS tool changers.

Description ID		Screw connection diagram
Adapter plate		
COS Z83-J/B	1610155	J

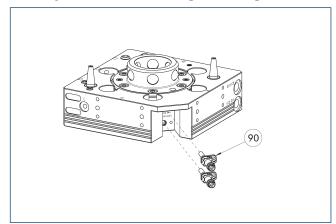
Tor detailed information and suitable cable connectors, see the "COB" chapter in the catalog, or visit schunk.com.

Optional modules COS



 For detailed information and suitable cable connectors, see the "COS" chapter in the catalog, or visit schunk.com.

Assembly situation of the locking monitoring



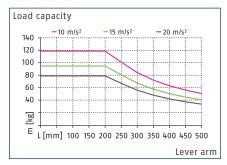
 Attachmient kit for lock/unlock monitoring (bracket and sensor)

The drawing shows the installation situation with the prepared locking monitoring.

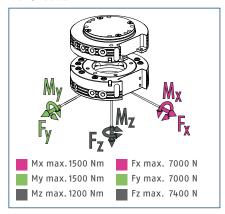
Description	ID
Attachment kit for pro	oximity switch
AS-CPS-046	1610159

The K-S variants of the CPS-K already have lock monitoring integrated, so there is no need to order an additional attachment kit. The scope of delivery of each attachment kit contains one preset sensor with bracket, meaning that two attachment kits are required per CPS-K.



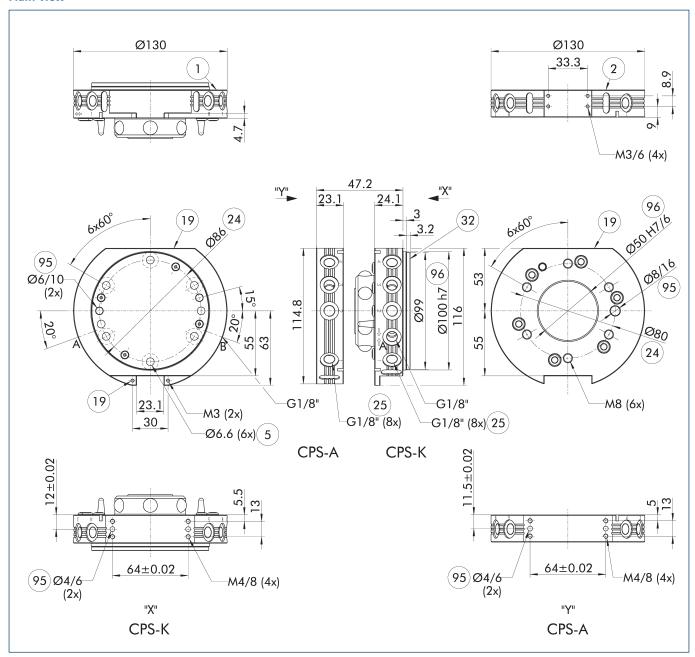


Max. loads



① This is the sum of all static loads that are permitted to act on the tool changer.

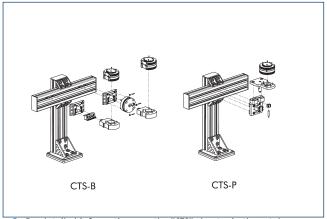
Description		CPS 060-K	CPS 060-A
		Change head	Tool
ID		1590997	1591020
Lock sensing		optional	
Locking force	[N]	7400	
Locking force provided by spring force	[N]	99	
Repeat accuracy	[mm]	0.015	
Weight	[kg]	1.3	0.7
Max. distance when locking	[mm]	3	
Number of pneumatic feed-throughs		8x G1/8"	8x G1/8"
Lock/unlock main connection		G1/8"	
Max. permissible XY axis offset	[mm]	±2	±2
Max. permissible angular offset XY	[°]	±0.6	±0.6
Max. permissible angular offset Z	[°]	±1	±1
Min./max. ambient temperature	[°C]	5/60	5/60
Min./max. operating pressure	[bar]	4.5/7	4.5/7
Screw connection diagram		K side A/ J via adapter plate side B	K side A/ J via adapter plate side B
Opening/closing time	[s]	0.3/0.1	
Cylinder volume per double stroke	[cm³]	82	
Max. volumetric flow per pneumatic feed-through		650 I/min (G1/8")	650 I/min (G1/8")
Max. dynamic moment Mx	[Nm]	500	500
Max. dynamic moment My	[Nm]	500	500
Max. dynamic moment Mz	[Nm]	400	400
Force Fx max. dynamic	[N]	2350	2350
Force Fy max. dynamic	[N]	2350	2350
Force Fz max. dynamic	[N]	2500	2500



The drawing shows the basic version of the tool changer without taking account of the dimensions of the options described below.

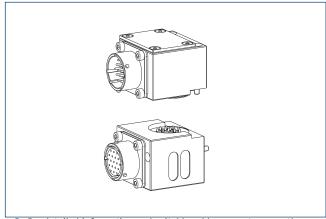
- The robot-side plate mounted on the CPS-K is a cover for the piston chamber. It is essential that it is supported by the adapter plate. See the further product information for a note on how to design this adapter plate.
- A, a Air connection locked
- B, b Air connection unlocked
- (1) Robot-side connection
- (2) Tool-side connection
- (5) Through hole for connection with screws
- (19) Mounting surface for options
- 24) Bolt circle
- **25** Pneumatic feed-throughs
- 32 Cover
- 95) Fit for centering pins
- 96) Fit for centering

Modular storage rack CTS



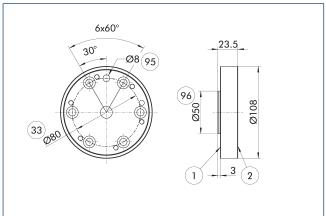
① For detailed information, see the "CTS" chapter in the catalog, or visit schunk.com.

Optional modules COS

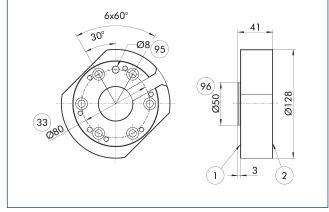


① For detailed information and suitable cable connectors, see the "COS" chapter in the catalog, or visit schunk.com.

Adapter plate ISO-A80-R



- 1 Robot-side connection
- 2 Tool-side connection
- 33 DIN ISO-9409 bolt circle
- 95) Fit for centering pins
 - 96 Fit for centering



1 Robot-side connection

Adapter plate ISO-A80-SIP-R

- 2 Tool-side connection
- 33 DIN ISO-9409 bolt circle
- 95) Fit for centering pins
- 96 Fit for centering

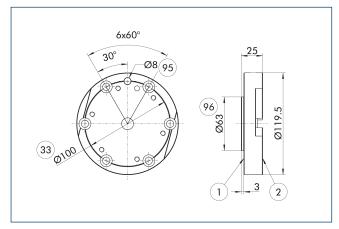
Robot side adapter plate

Description	ID
Adapter plate	
A-IS0080/CPS060	1581855

Robot side adapter plate

Description	ID	
Adapter plate		
A-IS0080/CPS060-SIP	1581857	

Adapter plate ISO-A100-R

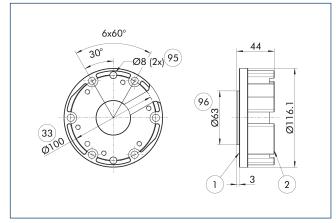


- 1 Robot-side connection
- 2 Tool-side connection
- 33 DIN ISO-9409 bolt circle
- 95 Fit for centering pins
- 96 Fit for centering

Robot side adapter plate

Description	ID
Adapter plate	
V-120100/CD20E0	1501057

Adapter plate ISO-A100-SIP-R

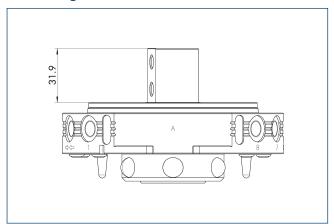


- 1 Robot-side connection
- 2 Tool-side connection
- 33 DIN ISO-9409 bolt circle
- 95 Fit for centering pins
- 96 Fit for centering

Robot side adapter plate

Description	ID
Adapter plate	
Δ-IS0100/CPS060-SIP	1581854

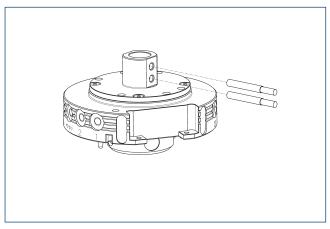
Lock sensing



The drawing shows the minimum height of the adapter plate required for installing locking monitoring.

Description	ID
Lock sensing	
AS-CPS-060-SIP-IN00	1596431

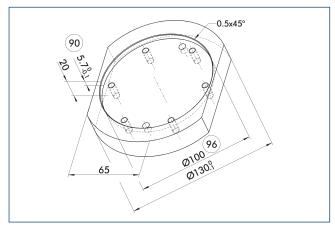
Lock sensing



Description	ID	Often combined
Inductive proximity switch		
IN 80-S-M12	0301578	
IN 80-S-M8	0301478	
INK 80-S	0301550	
Connection cables		
KA BG08-L 3P-0300-PNP	0301622	•
KA BG08-L 3P-0500-PNP	0301623	
KA BG12-L 3P-0500-PNP	30016369	
KA BW08-L 3P-0300-PNP	0301594	
KA BW08-L 3P-0500-PNP	0301502	
KA BW12-L 3P-0300-PNP	0301503	
KA BW12-L 3P-0500-PNP	0301507	
Clip for connector/socket		
CLI-M12	0301464	
CLI-M8	0301463	
Cable extension		
KV BG12-SG12 3P-0030-PNP	0301999	
KV BG12-SG12 3P-0060-PNP	0301998	
KV BW08-SG08 3P-0030-PNP	0301495	
KV BW08-SG08 3P-0100-PNP	0301496	
KV BW08-SG08 3P-0200-PNP	0301497	•
KV BW12-SG12 3P-0030-PNP	0301595	
KV BW12-SG12 3P-0100-PNP	0301596	
KV BW12-SG12 3P-0200-PNP	0301597	
Sensor distributor		
V2-M12	0301776	•
V2-M8	0301775	•
V4-M8	0301746	
V8-M8	0301751	

Per unit two sensors (closer/S) are required for each unit, as well as extension cables on option. Please consider the minimum permissible bending radii for sensor cables. These are generally 35 mm.

Adapter plate design

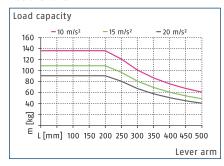


90 Recommended adapter plate depth

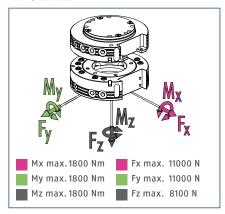
96 Fit for centering

Recommendation for the design of the adapter plate.



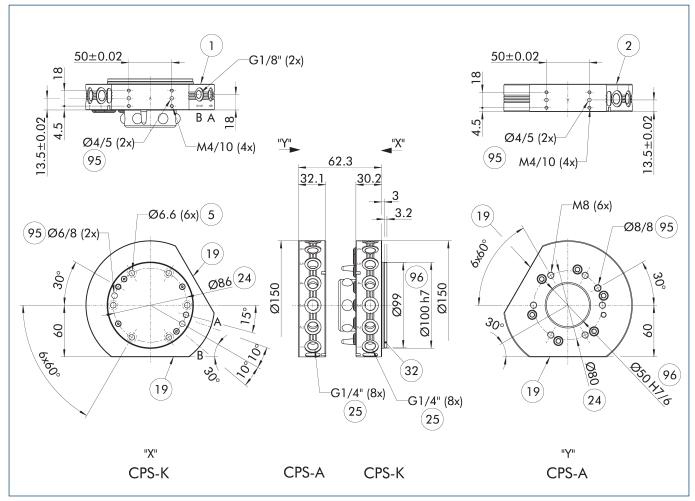


Max. loads



① This is the sum of all static loads that are permitted to act on the tool changer.

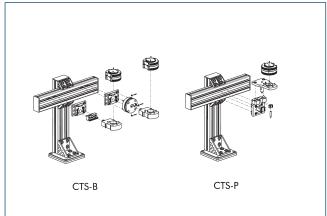
Description		CPS 071-K	CPS 071-A
Description			Tool
10		Change head	
ID		1591027	1591028
Lock sensing	Fug.	optional	
Locking force	[N]	8100	
Locking force provided by spring force	[N]	93	
Repeat accuracy	[mm]	0.015	
Weight	[kg]	2	1.3
Max. distance when locking	[mm]	3	
Number of pneumatic feed-throughs		8x G1/4"	8x G1/4"
Lock/unlock main connection		G1/8"	
Max. permissible XY axis offset	[mm]	±2	±2
Max. permissible angular offset XY	[°]	±0.6	±0.6
Max. permissible angular offset Z	[°]	±1	±1
Min./max. ambient temperature	[°C]	5/60	5/60
Min./max. operating pressure	[bar]	4.5/7	4.517
Screw connection diagram		2 x J	2 x J
Opening/closing time	[s]	0.3/0.1	
Cylinder volume per double stroke	[cm³]	81	
Max. volumetric flow per pneumatic feed-through		900 I/min (G1/4")	900 I/min (G1/4")
Max. dynamic moment Mx	[Nm]	600	600
Max. dynamic moment My	[Nm]	600	600
Max. dynamic moment Mz	[Nm]	600	600
Force Fx max. dynamic	[N]	3700	3700
Force Fy max. dynamic	[N]	3700	3700
Force Fz max. dynamic	[N]	2700	2700



The drawing shows the basic version of the tool changer without taking account of the dimensions of the options described below.

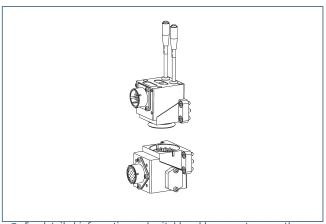
- The robot-side plate mounted on the CPS-K is a cover for the piston chamber. It is essential that it is supported by the adapter plate. See the further product information for a note on how to design this adapter plate.
- A, a Air connection locked
- B, b Air connection unlocked
- (1) Robot-side connection
- (2) Tool-side connection
- (5) Through hole for connection with screws
- 19 Mounting surface for options
- 24) Bolt circle
- 25) Pneumatic feed-throughs
- 32 Cover
- 95) Fit for centering pins
- 96 Fit for centering

Modular storage rack CTS



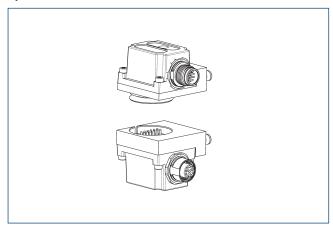
Tor detailed information, see the "CTS" chapter in the catalog, or visit schunk.com.

Optional modules COS



Tor detailed information and suitable cable connectors, see the "COS" chapter in the catalog, or visit schunk.com.

Optional modules COB

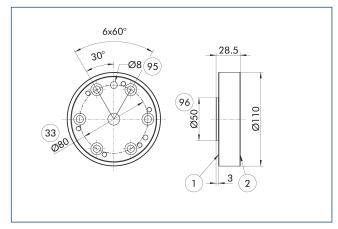


An adapter plate is required to mount COB option modules on CPS tool changers.

Description	ID	Screw connection diagram
Adapter plate		
COS Z83-J/B	1610155	J

For detailed information and suitable cable connectors, see the "COB" chapter in the catalog, or visit schunk.com.

Adapter plate ISO-A80-R

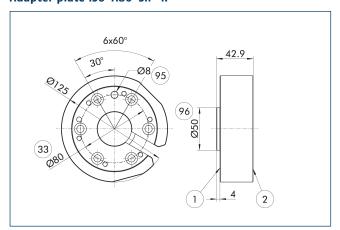


- 1 Robot-side connection
- 2 Tool-side connection
- 33 DIN ISO-9409 bolt circle
- 95 Fit for centering pins
- 96 Fit for centering

Robot side adapter plate

Description	ID
Adapter plate	
A-IS0080/CPS071	1581925

Adapter plate ISO-A80-SIP-R

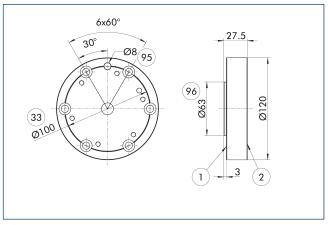


- 1) Robot-side connection
- (2) Tool-side connection
- 33 DIN ISO-9409 bolt circle
- 95) Fit for centering pins
- 96) Fit for centering

Robot side adapter plate

Description	ID
Adapter plate	
A-IS0080/CPS071-SIP	1581927

Adapter plate ISO-A100-R

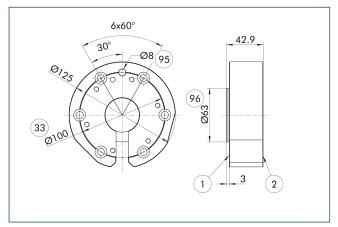


- 1) Robot-side connection
- (2) Tool-side connection
- 33 DIN ISO-9409 bolt circle
- 95) Fit for centering pins
- 96) Fit for centering

Robot side adapter plate

Description	ID
Adapter plate	
Δ-IS0100/CPS071	1581858

Adapter plate ISO-A100-SIP-R



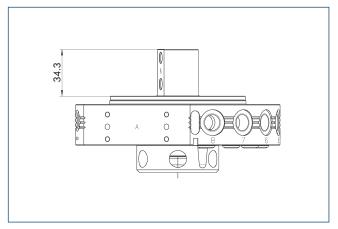
- 1 Robot-side connection
- 2 Tool-side connection
- 33 DIN ISO-9409 bolt circle

Robot side adapter plate

- 95 Fit for centering pins
- 96) Fit for centering

Description	ID
Adapter plate	
A-ISO100/CPS071-SIP	1581859

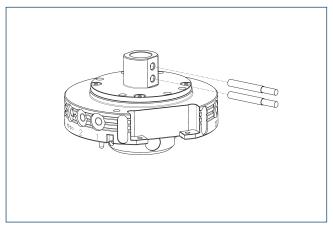
Lock sensing



The drawing shows the minimum height of the adapter plate required for installing locking monitoring.

Description	ID	
Lock sensing		
AS-CPS-071-SIP-IN00	1596432	

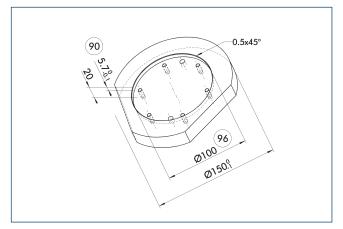
Lock sensing



Description	ID	Often combined
Inductive proximity switch		
IN 80-S-M12	0301578	
IN 80-S-M8	0301478	
INK 80-S	0301550	
Connection cables		
KA BG08-L 3P-0300-PNP	0301622	•
KA BG08-L 3P-0500-PNP	0301623	
KA BG12-L 3P-0500-PNP	30016369	
KA BW08-L 3P-0300-PNP	0301594	
KA BW08-L 3P-0500-PNP	0301502	
KA BW12-L 3P-0300-PNP	0301503	
KA BW12-L 3P-0500-PNP	0301507	
Clip for connector/socket		
CLI-M12	0301464	
CLI-M8	0301463	
Cable extension		
KV BG12-SG12 3P-0030-PNP	0301999	
KV BG12-SG12 3P-0060-PNP	0301998	
KV BW08-SG08 3P-0030-PNP	0301495	
KV BW08-SG08 3P-0100-PNP	0301496	
KV BW08-SG08 3P-0200-PNP	0301497	•
KV BW12-SG12 3P-0030-PNP	0301595	
KV BW12-SG12 3P-0100-PNP	0301596	
KV BW12-SG12 3P-0200-PNP	0301597	
Sensor distributor		
V2-M12	0301776	•
V2-M8	0301775	•
V4-M8	0301746	
V8-M8	0301751	

 Per unit two sensors (closer/S) are required for each unit, as well as extension cables on option. Please consider the minimum permissible bending radii for sensor cables. These are generally 35 mm.

Adapter plate design

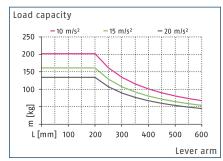


90 Recommended adapter plate depth

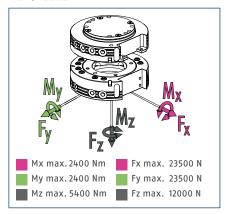
96 Fit for centering

Recommendation for the design of the adapter plate.



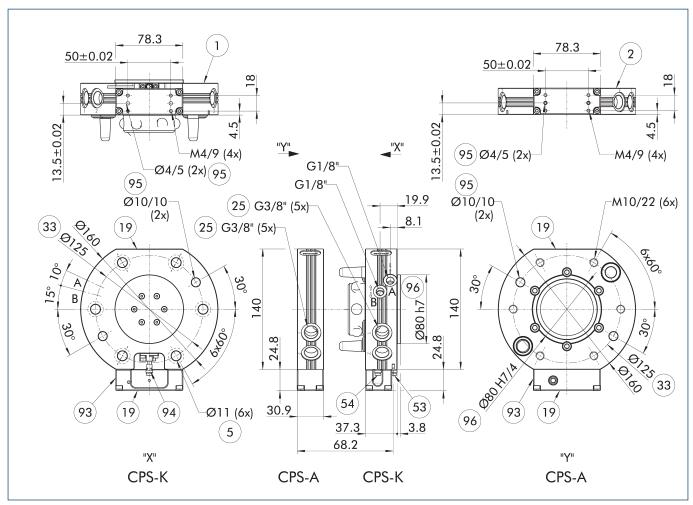


Max. loads



① This is the sum of all static loads that are permitted to act on the tool changer.

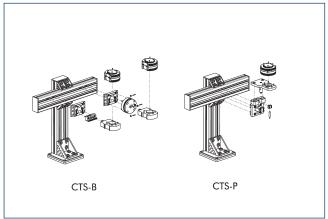
Description		CPS 076-K-S	CPS 076-K	CPS 076-A
		Change head	Change head	Tool
ID		1613287	1591031	1591035
Lock sensing		integrated	prepared	
Locking force	[N]	12000	12000	
Locking force provided by spring force	[N]	104	104	
Repeat accuracy	[mm]	0.015	0.015	
Weight	[kg]	2.6	2.6	1.4
Max. distance when locking	[mm]	2	2	
Number of pneumatic feed-throughs		5x G3/8"	5x G3/8"	5x G3/8"
Lock/unlock main connection		G1/8"	G1/8"	
Max. permissible XY axis offset	[mm]	±1	±1	±1
Max. permissible angular offset XY	[°]	±0.7	±0.7	±0.7
Max. permissible angular offset Z	[°]	±1	±1	±1
Robot-side connection		ISO 9409-1-125-6-M10	ISO 9409-1-125-6-M10	
Tool-side connection				ISO 9409-1-125-6-M10
Min./max. ambient temperature	[°C]	5/60	5/60	5/60
Min./max. operating pressure	[bar]	4.5/7	4.517	4.5/7
Screw connection diagram		2 x J	2 x J	2 x J
Opening/closing time	[s]	0.3/0.1	0.3/0.1	
Cylinder volume per double stroke	[cm³]	91	91	
Max. volumetric flow per pneumatic feed-through		1.400 I/min (G3/8")	1.400 I/min (G3/8")	1.400 I/min (G3/8")
Max. dynamic moment Mx	[Nm]	800	800	800
Max. dynamic moment My	[Nm]	800	800	800
Max. dynamic moment Mz	[Nm]	1800	1800	1800
Force Fx max. dynamic	[N]	7800	7800	7800
Force Fy max. dynamic	[N]	7800	7800	7800
Force Fz max. dynamic	[N]	4000	4000	4000



The drawing shows the basic version of the tool changer without taking account of the dimensions of the options described below.

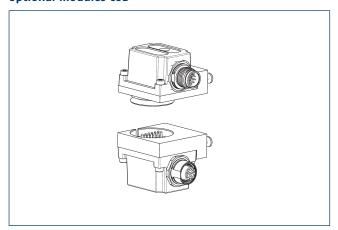
- A, a Air connection locked
- B, b Air connection unlocked
- (1) Robot-side connection
- 2 Tool-side connection
- (5) Through hole for connection with screws
- (19) Mounting surface for options
- 25) Pneumatic feed-throughs
- 33 DIN ISO-9409 bolt circle
- (53) Monitoring Position unlocked
- (54) Monitoring Position locked
- 93 Pre-assembled spacer adapter (included in the scope of delivery)
- 94) Optional proximity switch
- 95 Fit for centering pins
- 96) Fit for centering

Modular storage rack CTS



Tor detailed information, see the "CTS" chapter in the catalog, or visit schunk.com.

Optional modules COB

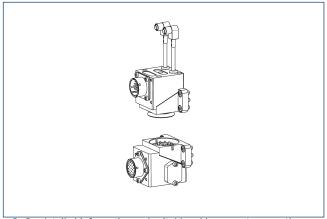


An adapter plate is required to mount COB option modules on CPS tool changers. $% \label{eq:condition}%$

Description	ID	Screw connection diagram
Adapter plate		
COS Z83-J/B	1610155	J

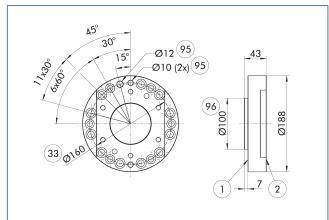
Tor detailed information and suitable cable connectors, see the "COB" chapter in the catalog, or visit schunk.com.

Optional modules COS



 For detailed information and suitable cable connectors, see the "COS" chapter in the catalog, or visit schunk.com.

Adapter plate ISO-A160-R

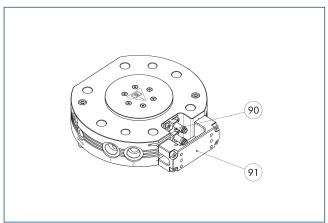


- 1 Robot-side connection
- 2 Tool-side connection
- 33 DIN ISO-9409 bolt circle
- 95 Fit for centering pins
- 96 Fit for centering

Robot side adapter plate

Description	ID
Adapter plate	
A-IS0160/CPS076	1581928

Assembly situation of the locking monitoring



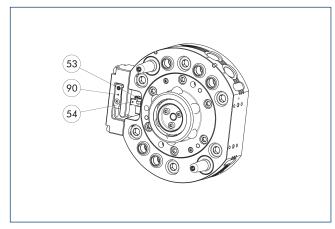
- Attachmient kit for lock/unlock monitoring (bracket and sensor)
- (included in the scope of delivery)

The drawing shows the installation situation with the prepared locking monitoring. A spacer adapter is required between the optional module and the CPS-K when using the integrated locking monitoring. The spacer adapter is included in the scope of delivery and is already pre-assembled. The spacer adapter is not required if the locking monitoring is not used.

Description	ID
Attachment kit for p	roximity swit
AS-CPS-040-076	1610160

The K-S variants of the CPS-K already have lock monitoring integrated, so there is no need to order an additional attachment kit. The scope of delivery of each attachment kit contains one preset sensor with bracket, meaning that two attachment kits are required per CPS-K.

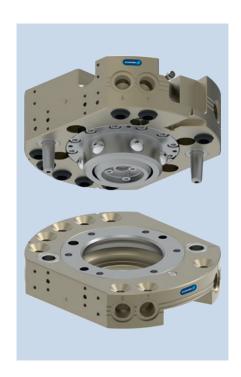
Installation situation presence monitoring

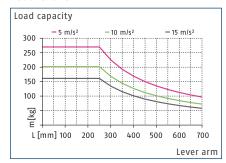


- (53) Monitoring Position unlocked
- 90 Sensor for presence control
- (54) Monitoring Position locked

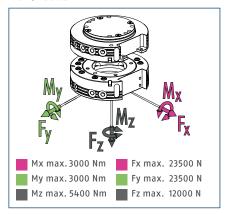
Description	ID
Inductive proximit	y switch
IN 8-SL-M8-SW	1622470
INK 8-SL	0302456

Tor each CPS-K, a proximity switch is required for presence monitoring.



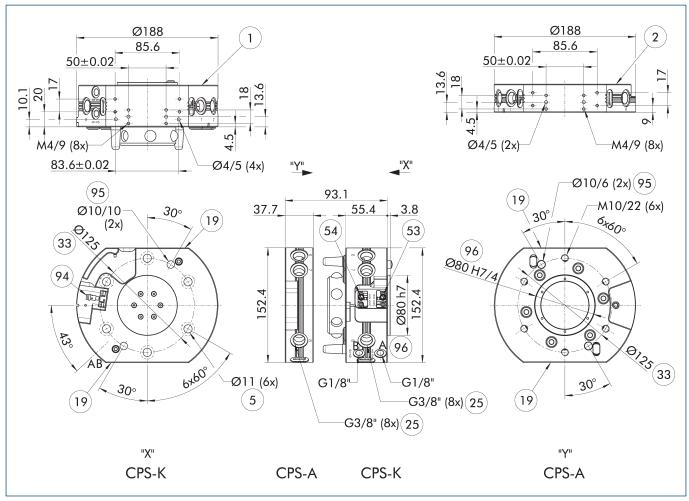


Max. loads



① This is the sum of all static loads that are permitted to act on the tool changer.

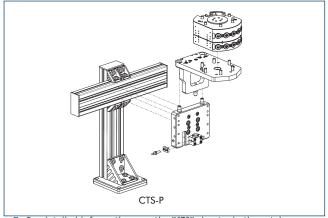
Description		CPS 110-K-S	CPS 110-K	CPS 110-A
		Change head	Change head	Tool
D		1613289	1590259	1590282
ock sensing		integrated	prepared	
ocking force	[N]	12000	12000	
ocking force provided by spring orce	[N]	230	230	
Repeat accuracy	[mm]	0.015	0.015	
Veight	[kg]	4.5	4.5	2.3
Max. distance when locking	[mm]	3	3	
Number of pneumatic Teed-throughs		8x G3/8"	8x G3/8"	8x G3/8"
.ock/unlock main connection		G1/8"	G1/8"	
Max. permissible XY axis offset	[mm]	±1	±1	±1
Max. permissible angular offset XY	[°]	±0.7	±0.7	±0.7
Max. permissible angular offset Z	[°]	±1	±1	±1
Robot-side connection		ISO 9409-1-125-6-M10	ISO 9409-1-125-6-M10	
Tool-side connection				ISO 9409-1-125-6-M10
Min./max. ambient temperature	[°C]	5/60	5/60	5/60
Min./max. operating pressure	[bar]	4.5/7	4.5/7	4.5/7
Screw connection diagram		2 x J	2 x J	2 x J
Opening/closing time	[s]	0.3/0.1	0.3/0.1	
Cylinder volume per double stroke	[cm³]	193	193	
Max. volumetric flow per pneumatic Teed-through		1.400 I/min (G3/8")	1.400 l/min (G3/8")	1.400 l/min (G3/8")
Max. dynamic moment Mx	[Nm]	1000	1000	1000
Max. dynamic moment My	[Nm]	1000	1000	1000
Max. dynamic moment Mz	[Nm]	1800	1800	1800
Force Fx max. dynamic	[N]	7800	7800	7800
Force Fy max. dynamic	[N]	7800	7800	7800
	[N]	4000	4000	4000



The drawing shows the basic version of the tool changer without taking account of the dimensions of the options described below.

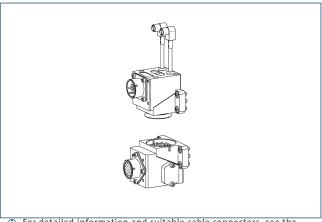
- A, a Air connection locked
- B, b Air connection unlocked
- (1) Robot-side connection
- 2 Tool-side connection
- (5) Through hole for connection with screws
- (19) Mounting surface for options
- 25 Pneumatic feed-throughs
- 33 DIN ISO-9409 bolt circle
- (53) Monitoring Position unlocked
- (54) Monitoring Position locked
- (94) Optional proximity switch
- 95) Fit for centering pins
- 96 Fit for centering

Modular storage rack CTS



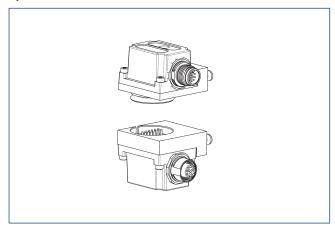
For detailed information, see the "CTS" chapter in the catalog, or visit schunk.com.

Optional modules COS



For detailed information and suitable cable connectors, see the "COS" chapter in the catalog, or visit schunk.com.

Optional modules COB

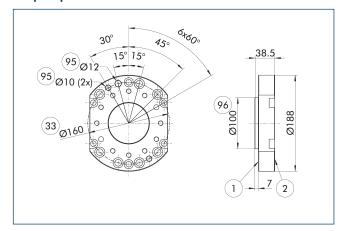


An adapter plate is required to mount COB option modules on CPS tool changers.

Description	ID	Screw connection diagram
Adapter plate		
COS Z83-J/B	1610155	J

Tor detailed information and suitable cable connectors, see the "COB" chapter in the catalog, or visit schunk.com.

Adapter plate ISO-A160-R



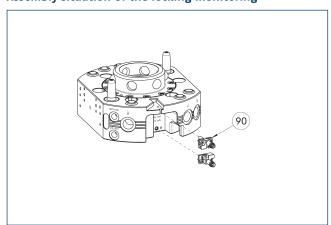
- 1 Robot-side connection
- 95) Fit for centering pins
- (2) Tool-side connection
- 96 Fit for centering
- 33 DIN ISO-9409 bolt circle

Robot side adapter plate

Description	ID
Adapter plate	
A-IS0160/CPS110-210	1581929

(i) Adapter plate for robots with M10 or M12 mounting patterns

Assembly situation of the locking monitoring



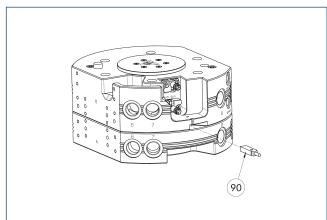
 Attachmient kit for lock/unlock monitoring (bracket and sensor)

The drawing shows the installation situation with the prepared locking monitoring.

Description	n	ID
Attachment	t kit for	proximity swit
AS-CPS-110	0-160	1610161

The K-S variants of the CPS-K already have lock monitoring integrated, so there is no need to order an additional attachment kit. The scope of delivery of each attachment kit contains one preset sensor with bracket, meaning that two attachment kits are required per CPS-K.

Installation situation presence monitoring

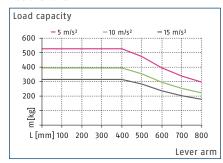


90 Sensor for presence control

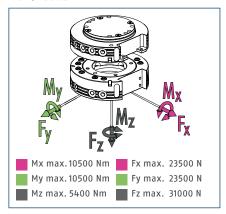
Description	ID
Inductive proximit	y switch
IN 8-SL-M8-SW	1622470
INK 8-SL	0302456

 $\ensuremath{\bigoplus}$ For each CPS–K, a proximity switch is required for presence monitoring.



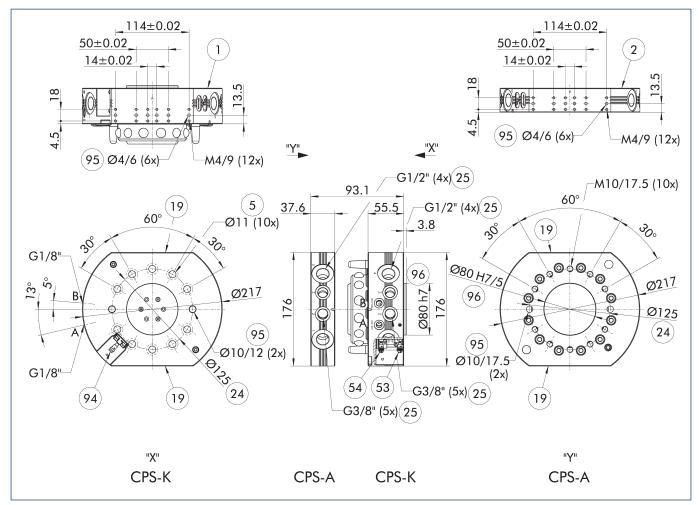


Max. loads



① This is the sum of all static loads that are permitted to act on the tool changer.

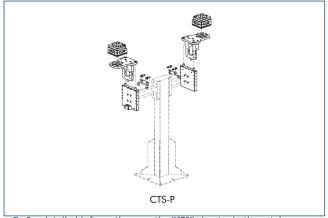
Description		CPS 160-K-S	CPS 160-K	CPS 160-A
		Change head	Change head	Tool
ID		1613301	1590284	1590286
Lock sensing		integrated	prepared	
Locking force	[N]	31000	31000	
Locking force provided by spring force	[N]	378	378	
Repeat accuracy	[mm]	0.015	0.015	
Weight	[kg]	7.6	7.6	3.1
Max. distance when locking	[mm]	2	2	
Number of pneumatic feed-throughs		5x G3/8"	5x G3/8"	5x G3/8"
Number of pneumatic feed-throughs		4x G1/2"	4x G1/2"	4x G1/2"
Lock/unlock main connection		G1/8"	G1/8"	
Max. permissible XY axis offset	[mm]	±2	±2	±2
Max. permissible angular offset XY	[°]	±0.7	±0.7	±0.7
Max. permissible angular offset Z	[°]	±1	±1	±1
Robot-side connection		ISO 9409-1-125-10-M10	ISO 9409-1-125-10-M10	
Tool-side connection				ISO 9409-1-125-10-M10
Min./max. ambient temperature	[°C]	5/60	5/60	5/60
Min./max. operating pressure	[bar]	4.5/7	4.5/7	4.5/7
Screw connection diagram		4 x J	4 x J	4 x J
Opening/closing time	[s]	0.3/0.1	0.3/0.3	
Cylinder volume per double stroke	[cm³]	279	279	
Max. volumetric flow per pneumatic feed-through		1.400 I/min (G3/8")	1.400 I/min (G3/8")	1.400 I/min (G3/8")
Max. volumetric flow per pneumatic feed-through		1.600 I/min (G1/2")	1.600 I/min (G1/2")	1.600 l/min (G1/2")
Max. dynamic moment Mx	[Nm]	3500	3500	3500
Max. dynamic moment My	[Nm]	3500	3500	3500
Max. dynamic moment Mz	[Nm]	1800	1800	1800
Force Fx max. dynamic	[N]	7800	7800	7800
Force Fy max. dynamic	[N]	7800	7800	7800
Force Fz max. dynamic	[N]	10500	10500	10500



The drawing shows the basic version of the tool changer without taking account of the dimensions of the options described below.

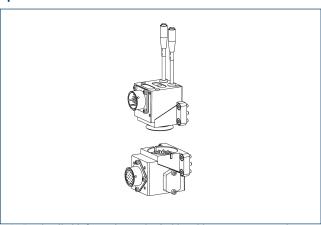
- A, a Air connection locked
- B, b Air connection unlocked
- (1) Robot-side connection
- 2 Tool-side connection
- (5) Through hole for connection with screws
- (19) Mounting surface for options
- 24) Bolt circle
- 25) Pneumatic feed-throughs
- (53) Monitoring Position unlocked
- (54) Monitoring Position locked
- (94) Optional proximity switch
- 95) Fit for centering pins
- 96 Fit for centering

Modular storage rack CTS



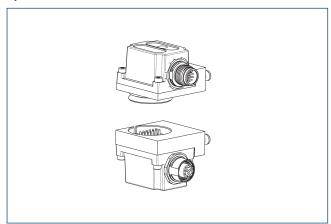
For detailed information, see the "CTS" chapter in the catalog, or visit schunk.com.

Optional modules COS



 For detailed information and suitable cable connectors, see the "COS" chapter in the catalog, or visit schunk.com.

Optional modules COB

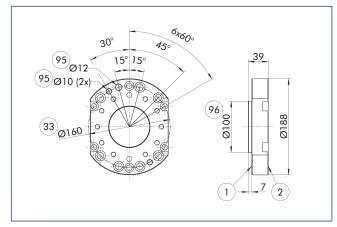


An adapter plate is required to mount COB option modules on CPS tool changers.

Description ID		D Screw connection diagram		
	Adapter plate			
	COS Z83-J/B	1610155	J	

Tor detailed information and suitable cable connectors, see the "COB" chapter in the catalog, or visit schunk.com.

Adapter plate ISO-A160-R

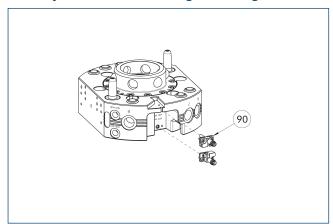


- 1 Robot-side connection
- 95) Fit for centering pins
- 2 Tool-side connection
- 96 Fit for centering
- 33 DIN ISO-9409 bolt circle

Robot side adapter plate

Description	ID
Adapter plate	
Δ-IS0160/CPS160	1581930

Assembly situation of the locking monitoring



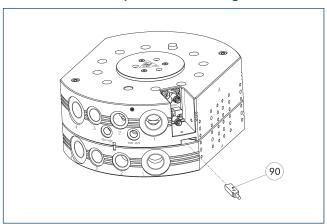
Attachmient kit for lock/unlock monitoring (bracket and sensor)

The drawing shows the installation situation with the prepared locking monitoring.

Description	ID	
Attachment kit for proximity swit		
AS-CPS-110-160	1610161	

The K-S variants of the CPS-K already have lock monitoring integrated, so there is no need to order an additional attachment kit. The scope of delivery of each attachment kit contains one preset sensor with bracket, meaning that two attachment kits are required per CPS-K.

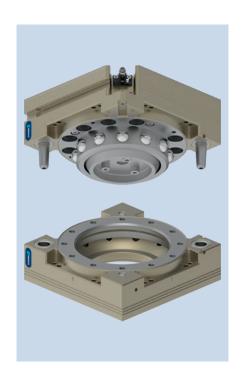
Installation situation presence monitoring

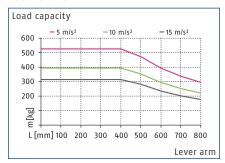


90 Sensor for presence control

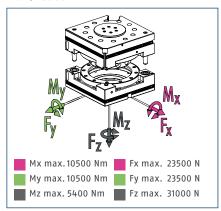
Description	ID
Inductive proximit	y switch
IN 8-SL-M8-SW	1622470
INK 8-SL	0302456

 $\ensuremath{\textcircled{\textbf{$\mathbb{D}}$}}$ For each CPS–K, a proximity switch is required for presence monitoring.





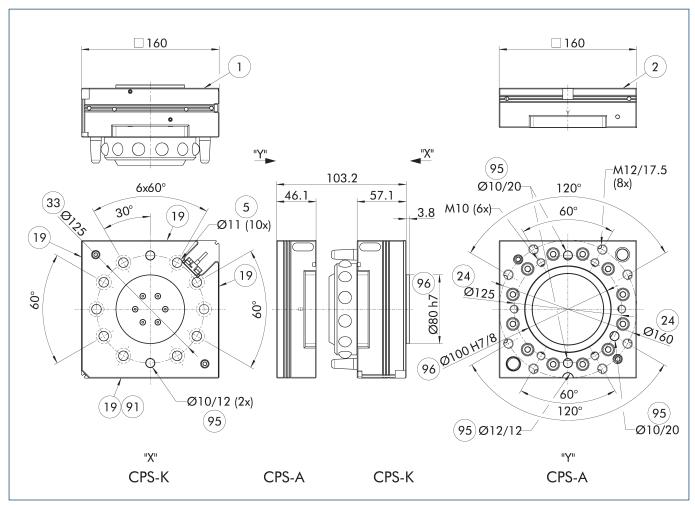
Max. loads



① This is the sum of all static loads that are permitted to act on the tool changer.

Description		CPS 210-K-S	CPS 210-A
		Change head	Tool
ID		1613303	1590994
Lock sensing		integrated	
Locking force	[N]	31000	
Locking force provided by spring force	[N]	378	
Repeat accuracy	[mm]	0.015	
Weight	[kg]	5.8	2.7
Max. distance when locking	[mm]	2	
Max. permissible XY axis offset	[mm]	±2	±2
Max. permissible angular offset XY	[°]	±0.7	±0.7
Max. permissible angular offset Z	[°]	±1	±1
Robot-side connection		ISO 9409-1-125-6-M10	
Tool-side connection			ISO 9409-1-125-6-M10
Min./max. ambient temperature	[°C]	5/60	5/60
Min./max. operating pressure	[bar]	5/7	5/7
Screw connection diagram		L1 side A/L side B/C/D	L side A/B/C/D
Mounting surface control module		Side A	Side A
Opening/closing time	[s]	0.3/0.1	
Cylinder volume per double stroke	[cm³]	314	
Max. dynamic moment Mx	[Nm]	3500	3500
Max. dynamic moment My	[Nm]	3500	3500
Max. dynamic moment Mz	[Nm]	1800	1800
Force Fx max. dynamic	[N]	7800	7800
Force Fy max. dynamic	[N]	7800	7800
Force Fz max. dynamic	[N]	10500	10500

Main view

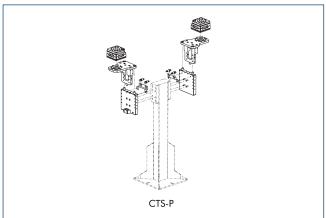


The drawing shows the basic version of the tool changer without taking account of the dimensions of the options described below.

- 1 Robot-side connection
- 2 Tool-side connection
- (5) Through hole for connection with screws
- (19) Mounting surface for options
- 24) Bolt circle

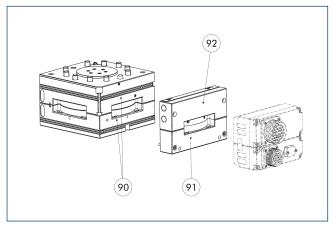
- (33) DIN ISO-9409 bolt circle
- (91) Mounting surface A for control modules
- 95 Fit for centering pins
- 96 Fit for centering

Modular storage rack CTS



Tor detailed information, see the "CTS" chapter in the catalog, or visit schunk.com.

Pneumatic control module

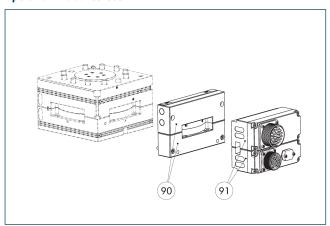


- 90 Mounting surface A for control modules
- 91) Distance plate
- (92) Pneumatic control module

An additional pneumatic control module is required on the CPS-K for locking and unlocking, which is available in different versions. The simple version includes 2 air connections for locking and unlocking, and a customer-side pneumatic valve is required. The other variant already includes a pneumatic valve in the module, which is connected to the piston chamber of the CPS-K and locks and unlocks the tool changer.

Tor detailed information and suitable cable connectors, see the "COS" chapter in the catalog, or visit schunk.com.

Optional modules COS

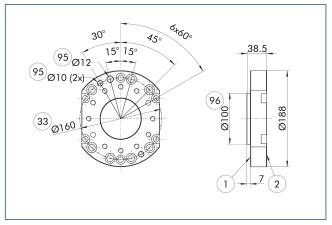


- 90 Pneumatic control module and spacer plate
- (91) Optional module COS

It is possible to screw additional COS option modules onto the pneumatic control module and the distance plate.

Tor detailed information and suitable cable connectors, see the "COS" chapter in the catalog, or visit schunk.com.

Adapter plate ISO-A160-R



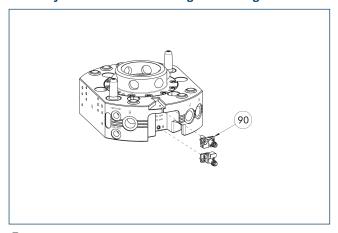
- (1) Robot-side connection
- (2) Tool-side connection
- 33 DIN ISO-9409 bolt circle
- 95 Fit for centering pins
- 96) Fit for centering

Robot side adapter plate

Description	ID
Adapter plate	
A-IS0160/CPS110-210	1581929

① Adapter plate for robots with M10 or M12 mounting patterns

Assembly situation of the locking monitoring



Attachmient kit for lock/unlock monitoring (bracket and sensor)

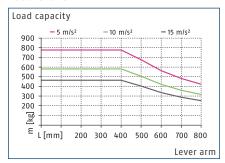
The drawing shows the installation situation with the prepared locking monitoring.

Description	ID
Attachment kit for p	oximity switch
AS-CPS-210	1620279

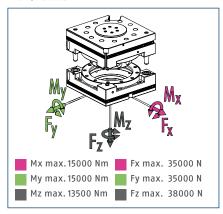
The K-S variants of the CPS-K already have lock monitoring integrated, so there is no need to order an additional attachment kit. The scope of delivery of each attachment kit contains one preset sensor with bracket, meaning that two attachment kits are required per CPS-K.



Load chart



Max. loads

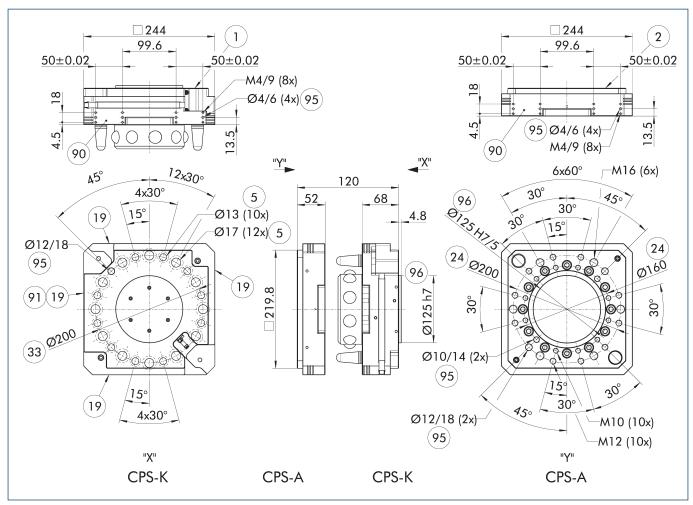


① This is the sum of all static loads that are permitted to act on the tool changer.

Technical data

Description		CPS 310-K-S	CPS 310-A
		Change head	Tool
ID		1613305	1590996
Lock sensing		integrated	
Locking force	[N]	38000	
Locking force provided by spring force	[N]	574	
Repeat accuracy	[mm]	0.015	
Weight	[kg]	13.4	7.3
Max. distance when locking	[mm]	2.5	
Max. permissible XY axis offset	[mm]	±2	±2
Max. permissible angular offset XY	[°]	±0.7	±0.7
Max. permissible angular offset Z	[°]	±1	±1
Robot-side connection		ISO 9409-1-200-6-M12	
Tool-side connection			ISO 9409-1-200-6-M12
Min./max. ambient temperature	[°C]	5/60	5/60
Min./max. operating pressure	[bar]	5/7	517
Screw connection diagram		L2 side A/L side B/C/D	L side A/B/C/D
Mounting surface control module		Side A	Side A
Opening/closing time	[s]	0.5/0.5	
Cylinder volume per double stroke	[cm³]	581	
Max. dynamic moment Mx	[Nm]	5000	5000
Max. dynamic moment My	[Nm]	5000	5000
Max. dynamic moment Mz	[Nm]	4500	4500
Force Fx max. dynamic	[N]	11500	11500
Force Fy max. dynamic	[N]	11500	11500
Force Fz max. dynamic	[N]	12500	12500

Main view



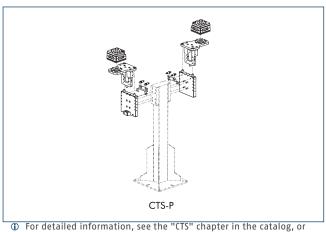
The drawing shows the basic version of the tool changer without taking account of the dimensions of the options described below.

- (1) Robot-side connection
- 2 Tool-side connection
- (5) Through hole for connection with screws
- (19) Mounting surface for options
- 24) Bolt circle

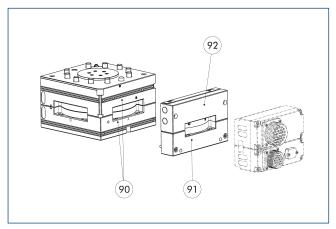
- 33 DIN ISO-9409 bolt circle
- 90 Screw connection diagram also on the opposite side
- (91) Mounting surface A for control modules
- 95) Fit for centering pins
- 96 Fit for centering

Modular storage rack CTS

visit schunk.com.



Pneumatic control module

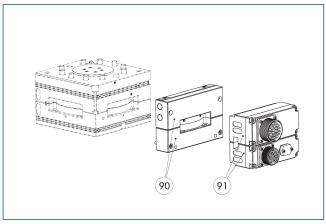


- 90 Mounting surface A for control modules
- 91) Distance plate
- (92) Pneumatic control module

An additional pneumatic control module is required on the CPS-K for locking and unlocking, which is available in different versions. The simple version includes 2 air connections for locking and unlocking, and a customer-side pneumatic valve is required. The other variant already includes a pneumatic valve in the module, which is connected to the piston chamber of the CPS-K and locks and unlocks the tool changer.

Tor detailed information and suitable cable connectors, see the "COS" chapter in the catalog, or visit schunk.com.

Optional modules COS

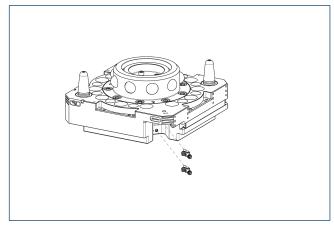


- 90 Pneumatic control module and spacer plate
- 91) Optional module COS

It is possible to screw additional COS option modules onto the pneumatic control module and the distance plate.

Tor detailed information and suitable cable connectors, see the "COS" chapter in the catalog, or visit schunk.com.

Assembly situation of the locking monitoring



Attachmient kit for lock/unlock monitoring (bracket and sensor)

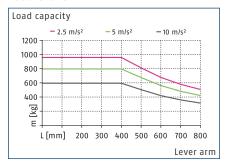
The drawing shows the installation situation with the prepared locking monitoring.

Description	ID	
Attachment kit for pr	oximity switch	1
AS-CPS-310	1610162	

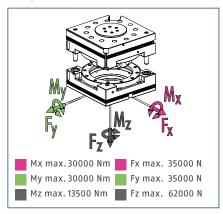
The K-S variants of the CPS-K already have lock monitoring integrated, so there is no need to order an additional attachment kit. The scope of delivery of each attachment kit contains one preset sensor with bracket, meaning that two attachment kits are required per CPS-K.



Load chart



Max. loads

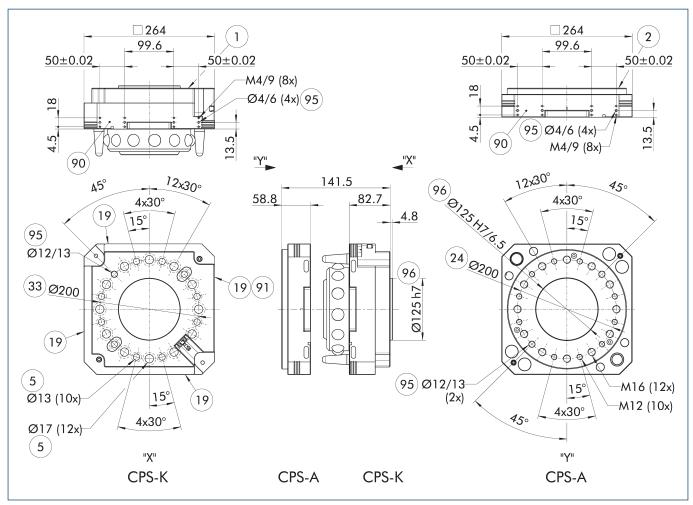


① This is the sum of all static loads that are permitted to act on the tool changer.

Technical data

Description		CPS 510-K-S	CPS 510-A
		Change head	Tool
ID		1613306	1590999
Lock sensing		integrated	
Locking force	[N]	62000	
Locking force provided by spring force	[N]	710	
Repeat accuracy	[mm]	0.015	
Weight	[kg]	19.7	8.7
Max. distance when locking	[mm]	2.5	
Max. permissible XY axis offset	[mm]	±2	±2
Max. permissible angular offset XY	[°]	±0.7	±0.7
Max. permissible angular offset Z	[°]	±1	±1
Robot-side connection		ISO 9409-1-200-6-M12	
Tool-side connection			ISO 9409-1-200-6-M12
Min./max. ambient temperature	[°C]	5/60	5/60
Min./max. operating pressure	[bar]	517	5/7
Screw connection diagram		L2 side A/L side B/C/D	L side A/B/C/D
Mounting surface control module		Side A	Side A
Opening/closing time	[s]	0.5/0.1	
Cylinder volume per double stroke	[cm³]	1080	
Max. dynamic moment Mx	[Nm]	10000	10000
Max. dynamic moment My	[Nm]	10000	10000
Max. dynamic moment Mz	[Nm]	4500	4500
Force Fx max. dynamic	[N]	11800	11800
Force Fy max. dynamic	[N]	11800	11800
Force Fz max. dynamic	[N]	20500	20500

Main view

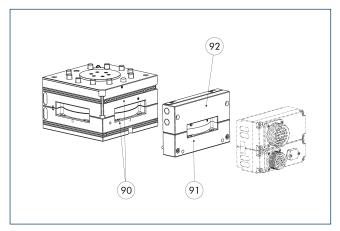


The drawing shows the basic version of the tool changer without taking account of the dimensions of the options described below.

- 1 Robot-side connection
- 2 Tool-side connection
- (5) Through hole for connection with screws
- (19) Mounting surface for options
- 24) Bolt circle

- 33 DIN ISO-9409 bolt circle
- 90 Screw connection diagram also on the opposite side
- (91) Mounting surface A for control modules
- 95) Fit for centering pins
- 96 Fit for centering

Pneumatic control module

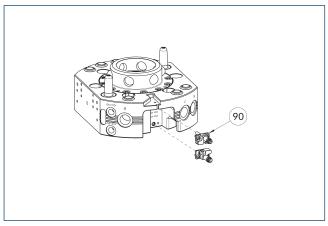


- 90 Mounting surface A for control modules
- (91) Distance plate
- (92) Pneumatic control module

An additional pneumatic control module is required on the CPS-K for locking and unlocking, which is available in different versions. The simple version includes 2 air connections for locking and unlocking, and a customer-side pneumatic valve is required. The other variant already includes a pneumatic valve in the module, which is connected to the piston chamber of the CPS-K and locks and unlocks the tool changer.

Tor detailed information and suitable cable connectors, see the "COS" chapter in the catalog, or visit schunk.com.

Assembly situation of the locking monitoring



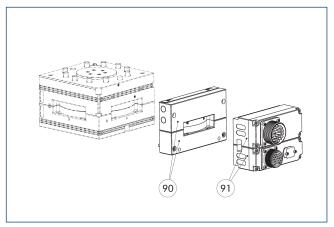
Attachmient kit for lock/unlock monitoring (bracket and sensor)

The drawing shows the installation situation with the prepared locking monitoring.

Description	ID
Attachment kit for pro	oximity switch
AS-CPS-510	1620282

The K-S variants of the CPS-K already have lock monitoring integrated, so there is no need to order an additional attachment kit. The scope of delivery of each attachment kit contains one preset sensor with bracket, meaning that two attachment kits are required per CPS-K.

Optional modules COS



- 90 Pneumatic control module and spacer plate
- 91) Optional module COS

It is possible to screw additional COS option modules onto the pneumatic control module and the distance plate.

 For detailed information and suitable cable connectors, see the "COS" chapter in the catalog, or visit schunk.com.



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